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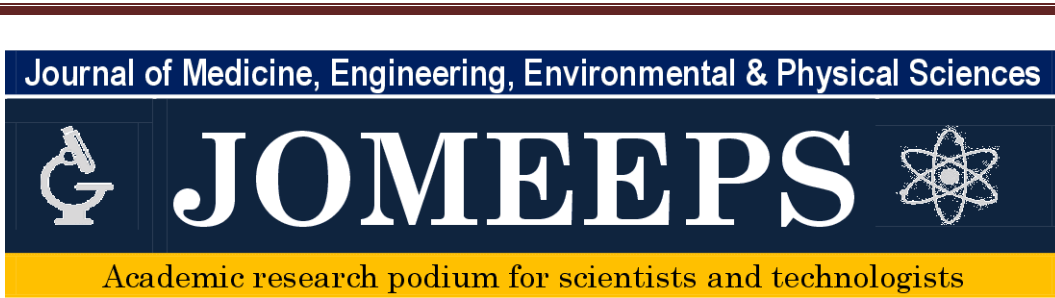
Applications of Information Cryptography in Its Various Stages of Evolution, from Antiquity to the Modern Era

Use of Fenton's Reagent for Pollutants Removal in Pharmaceutical Effluent



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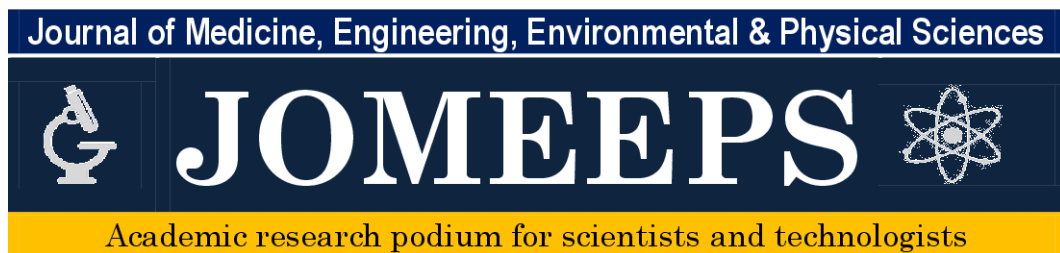
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Protective Roles of Quercetin, Vitamin C and Pyridoxine on Lead Neurotoxicity via Enhanced Haematopoietic and Antioxidants Components

By

Nnachi Ifenna Salvator, Elizabeth Finbarrs-Bello, Ozor Ignatius Ikemefuna, Mba Christian Ejuiwa, & Vivian Ugwu

Abstract

Background: The harmful effects of lead exposure, especially its effect on the nervous system, raise serious concerns worldwide. This study is aimed at evaluating the effect of Quercetin, Vitamin C and Pyridoxine on Haematology, biochemical and histology of the cerebral cortex on lead induced neurotoxicity using adult Wistar rat models. **Materials and Methods:** Forty male Wistar albino rats were divided into five groups: control, lead only, lead + Quercetin, lead + Pyridoxine, lead and Vitamin C. 100mg/kg/bw of lead was used to induce-toxicity for 7 days and treated with the following: Quercetin, Pyridoxine and Vitamin C were administrated orally respectively for 14 days. Hematological and biochemical samples were collected in three phases. The cerebral cortex was examined under light microscopy after H&E staining. **Results:** lead decreased all hematological parameters (PCV, WBC, RBC, HB and Platelets) examined and in the biochemical parameters, decreased slightly SOD, increased MDA and reduced significantly (p values) GSH. Quercetin, Vitamin C and Pyridoxine had strong curative effects on both hematological and biochemical parameters. On the histology, lead revealed mild glial cell infiltration. All treatment groups showed normal neuronal cells. **Conclusion:** Quercetin, Vitamin C and Pyridoxine showed neuroprotective effects against lead-induced neurotoxicity; therefore, they can be used as routine supplements against lead toxicity in endemic communities.

Keywords: Quercetin, Pyridoxine, Lead, Ascorbic acid, neurotoxicity, lipid peroxidation

Introduction

Lead (Pb) is one of the most widely used heavy metals, especially in batteries, paint pigments, and plastics. This heavy use has produced local and global contamination of the air, soil, and water originating from lead-based pipes. The effect of exposure to Pb vary from mild to severe, depending on the degree of exposure, and is referred to as lead toxicity (Raymond, 2011). The nervous system (central and peripheral components) is the primary target of lead poisoning or toxicity (Brent, 2006; Bellinger, 2004). Pb toxicity is also known to induce a broad range of hematological, biochemical, and histomorphological dysfunctions in lab animals and humans (Hsu & Guo, 2002; Pande & Flora

2002). This is characterized by persistent vomiting, anemia, encephalopathy, lethargy, delirium, convulsions and coma, and death in extreme cases (Flora et al., 2006; Pearce, 2007). One of the possible mechanisms underlying Pb-induced toxicity or poisoning is its ability to induce oxidative stress in blood and other tissues, which contributes to the pathogenesis of poisoning by interfering with the delicate prooxidant/antioxidant balance that exists within the mammalian cells. Several investigators suggest a possible involvement of reactive oxygen species (ROS) in Pb-induced toxicity (Adonaylo & Oteiza, 1999; Pande & Flora, 2002; Hsu & Guo, 2002) where Pb increased lipid peroxidation indicator the malondialdehyde (MDA) and decreased the activities of antioxidants enzymes: glutathione peroxidase (GPx), and superoxide dismutase (SOD) in the rat brains (Kuhad & Chopra, 2007).

Antioxidants have been identified to protect the neurons against various experimental neurodegenerative conditions (Kuhad & Chopra, 2007). Vitamin C, vitamins E and B6, zinc, and selenium are antioxidants used to reverse Pb-mediated toxicity by ameliorating oxidative stress status (Hsu & Guo, 2002). Flavonoids have now become a topic of interest due to their beneficial effects on different diseases. Quercetin is a natural flavonoid, ubiquitously found in common fruits and vegetables such as onions, broccoli, and apples (Sriraksa et al., 2016). Studies have reported that quercetin exhibits substantial antioxidant property, has the ability to scavenge free radicals, and aids many biological processes involved in oxidative stress (Formica et al., 1995). This study, therefore, evaluates the hematological, biochemical, and histomorphological effects of Quercetin, Vitamin C and Pyridoxine on lead-induced neurotoxicity in adult Wistar rats.

Materials and Methods

Procurement of Compounds, Chemical and Drugs

5g of Quercetin was procured from Zigma, Aldrich USA. Lead (Pb) weight of 5.2g was procured from registered chemical store at Ogbete main market Enugu Metropolis, Nigeria. 5g of Vitamin C (ascorbic acid) and Pyridoxine (Vitamin B6) were procured from Omaryon group of companies Enugu Metropolis, Nigeria.

Animal Handling

Forty (40) Wistar rats weighing between 150 - 250g were purchased from the animal house of the University of Nigeria, Nsukka, Enugu State, Nigeria. The rats were housed at the animal facility of the College of Medicine, Enugu State University of Science and Technology Enugu Nigeria. The rats were housed for a period of 4 weeks to attain desired weights and to get them acclimatized in their new environment. The rats were fed pelleted rat chow (Vital, Nig. Ltd.)

and allowed water *ad libitum*. Thereafter, the rats were grouped into five (5) groups; each group had eight rats housed in two different cages 2 (n=4) per group. The rats were kept in ventilated cages at optimum temperature 28°C with 12 hours light/dark cycle, and humidity of 60%. The study was reviewed and approved by the Faculty Ethics and Research Committee.

Induction of Lead Toxicity

The used dose for lead induction was adopted from Highab et al., (2018), 100 mg /kg/bw of lead was administered orally for 7days across groups. Thereafter, Quercetin was administered as modified using methods of Tian *et al.*, 2019, at 50mg /kg / bw). Vitamin C and Pyridoxine (Vitamin B6) were used as standard drug for the experiment, the doses were adopted from Razmkon *et al.*, (2011) at dosage 500 mg /kg /bw for Vitamin C and 100 mg/ kg/ bwt for Pyridoxine (Vitamin B6).all treatment were administered via oral gavage for 14 days.

Experimental Design

Group	Description of Treatments
GROUP A	Control group – 0.1mL Normal Saline
GROUP B	Treatment group: Lead 100 mg/kg + Pyridoxine 100 mg/k/ body weight
GROUP C	Treatment group: Lead 100 mg/kg + Quercetin 50 mg/k/ body weight
GROUP D	Treatment group: Lead 100 mg/kg + Vitamin C 500 mg/kg/body weight
GROUP E	Negative control: Lead 100 mg/kg/body weight

Hematological and Biochemical Evaluations

Blood samples were collected from all the rats thrice to form a baseline, after induction and after treatment as well as parameter for post induction. Materials used for collection of samples are; capillary tubes and plain EDTA bottles. The following were evaluated; PCV, WBC, RBC, HB, and Platelets for hematological studies using standard protocols. While serum Superoxide dismutase (SOD), Malondialdehyde (MDA) & Glutathione (GSH) antioxidant marker enzyme were determined using the respective kit in accordance with manufacturers recommended protocols (Fortress diagnostic limited UK). Measurement of Malondialdehyde (MDA), a prototype of the thiobarbituric reactive substances (TBARS) as a biomarker of lipid peroxidation and oxidative stress using modified thiobarbituric acid method (Todorova et al., 2005).The IBM SPSS package (IBM Corp., IBM SPSS Statistics for Windows, Version 25.0, Armonk, NY, USA),was used to analyze the data. Descriptive statistics was evaluated for hematological and antioxidative markers and presented as means and standard deviations. An analysis of variance test (One-way ANOVA) was used for comparison of the means for the hematological, and antioxidant enzymes. The P values for comparing means were considered significant at $p \geq 0.05$.

Termination of Study and Tissue Collection

On the 15th day (day one post treatment), the rats in all groups were sacrificed under light ether and the brains were harvested. The brains were fixed in 10% neutral formal saline for 48hrs. Thereafter the cerebrum were isolated for routine paraffin processing and stained with Haematoxylin and Eosin. Representative photomicrographs were captured after the interpretation.

Results

Hematological Analysis

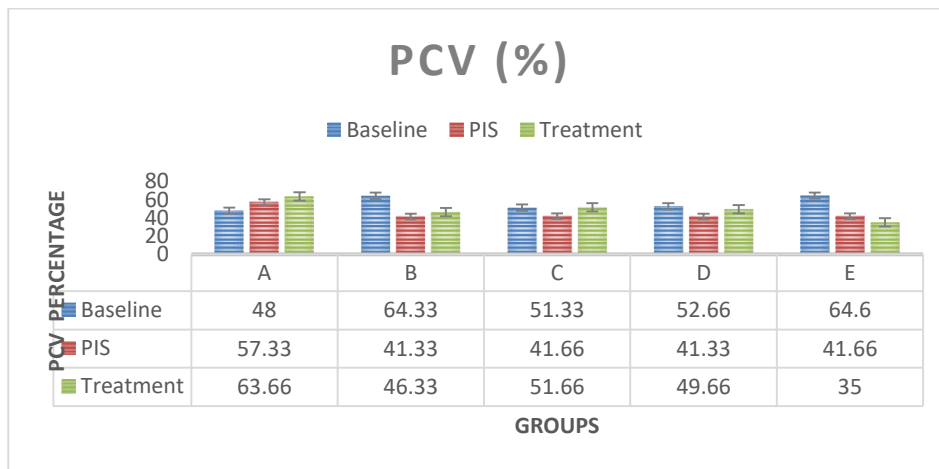


Figure 1: Shows PCV test results across groups. The PCV values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. In group E (Lead only), the PCV values regressed with continuous administration. Treatment groups B, C and D was observed to have increased PCV values after treatment which is similar when compared to observations in control group A. However, PCV values were not significant ($P > 0.05$) in paired sample correlations across groups in 2nd and 3rd study.

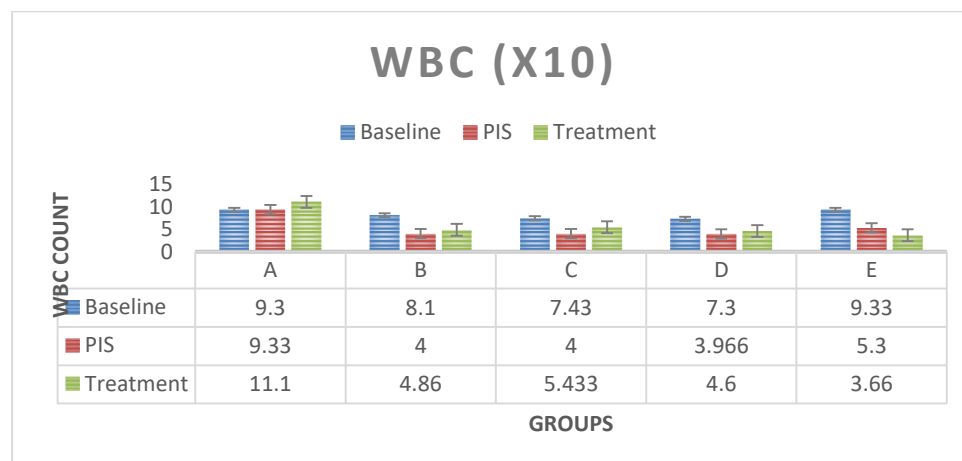


Figure 2: Shows WBC test results across groups. The WBC values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. In group E (Lead only), the WBC count was significantly lower ($P < 0.05$) compared to the control group A and treatment groups B, C and D. WBC values was observed to increase after treatment across treatment groups. WBC count was also significant ($P < 0.05$) in paired sample correlations across groups in 2nd and 3rd studies respectively.

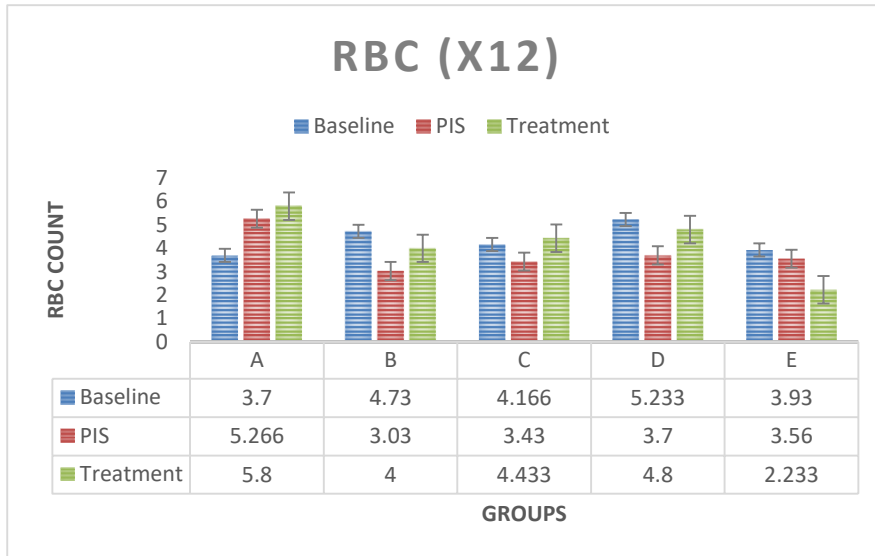


Figure 3: RBC test results across groups. The RBC values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. RBC values was reduced in the post induction study (2nd study) and increased at the treatment study across treatment groups (B, C & D) in comparison to lead only (E) group, which registered steady decline in RBC values. Paired sample correlates across groups in 2nd study and 3rd study groups also showed no significant difference ($P > 0.05$).

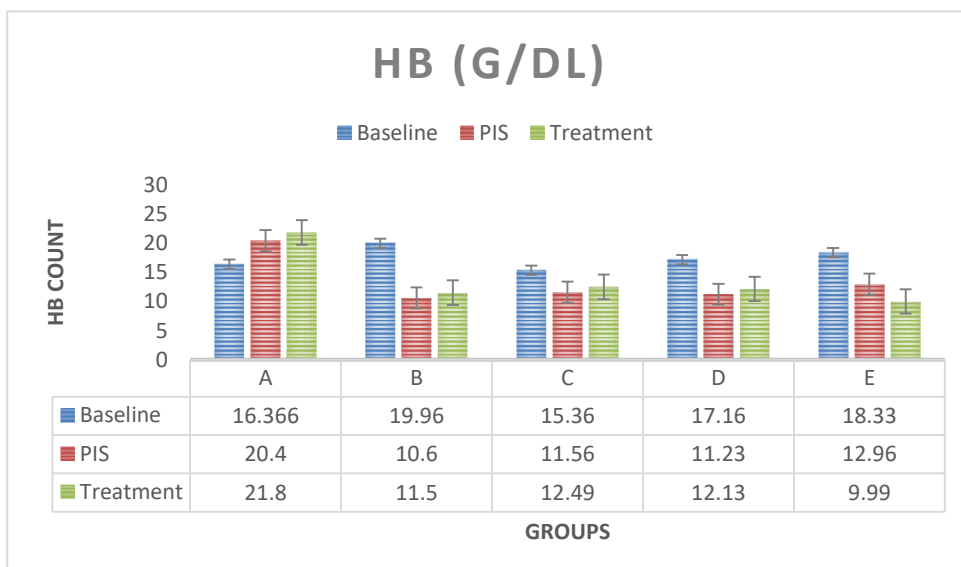


Figure 4: The figure above shows HB test results across groups. The HB values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. Hemoglobin values was lower with continuous administration in group E (lead only group), in comparison to control group A and treatment group B, C and D. however, HB values was seen to reduce in the post induction study results and increase in the treatment study result across treatment groups. hemoglobin was significant ($P < 0.05$) in paired sample correlation across groups in post induction (2nd study) and post treatment (3rd study) groups.

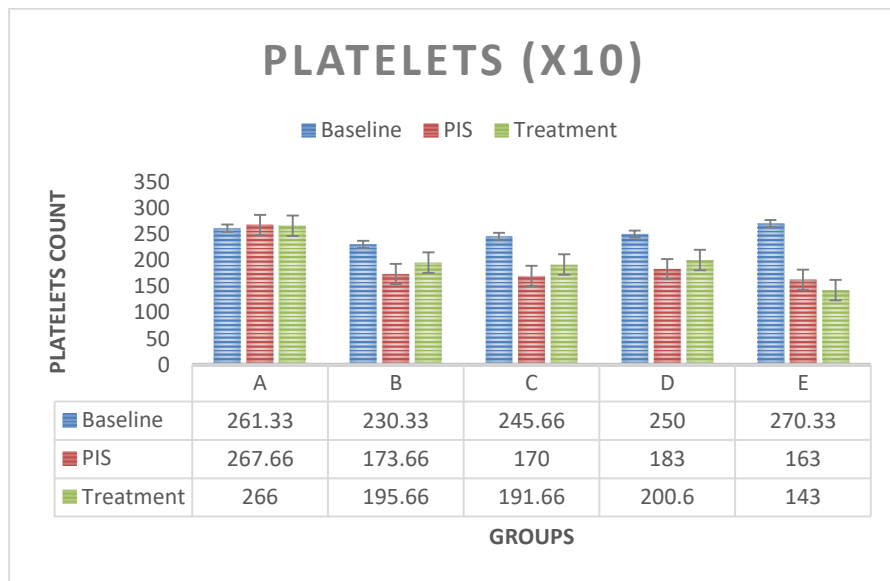


Figure 5: Platelets test results across groups. The platelets values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. Platelets values were continuously decreased in group E (Lead only) but there was no difference between treatment groups C, D and B. Platelet values were reduced in post induction study and increased in treatment group across treatment groups in comparison to control group A. However, paired sample correlations were significant ($P < 0.05$) across groups.

Biochemical: Antioxidant Evaluation

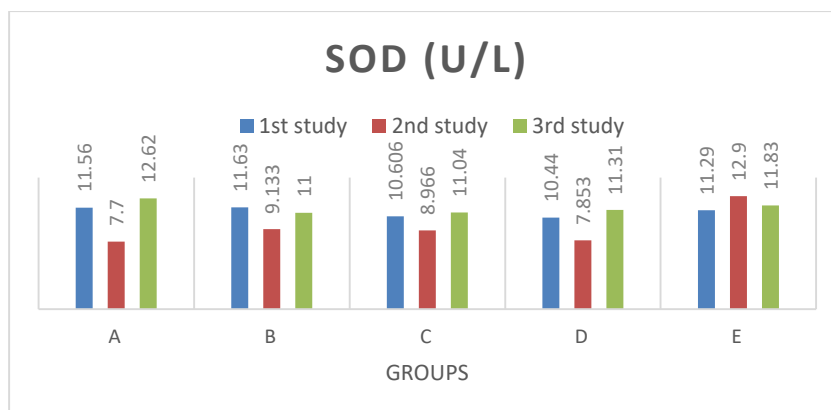


Figure 6; Shows SOD test results across groups. The SOD values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. There was no significant difference ($P > 0.05$) in SOD values across all groups. Also consistent with paired sample correlation of 2nd and 3rd study.

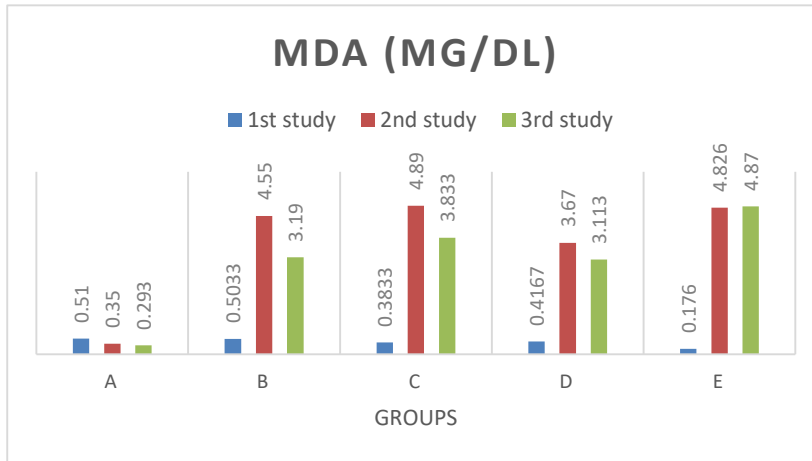


Figure 7; Shows MDA test results across groups. The MDA values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. In group E (lead only), MDA values increased at continuous induction of lead in comparison to control group A, treatment group B (lead and pyridoxine), C (lead and quercetin) and D (lead and ascorbic acid) where values were reduced after treatment. Values were significant at $P < 0.05$ across groups. Also consistent with findings from paired sample correlation.

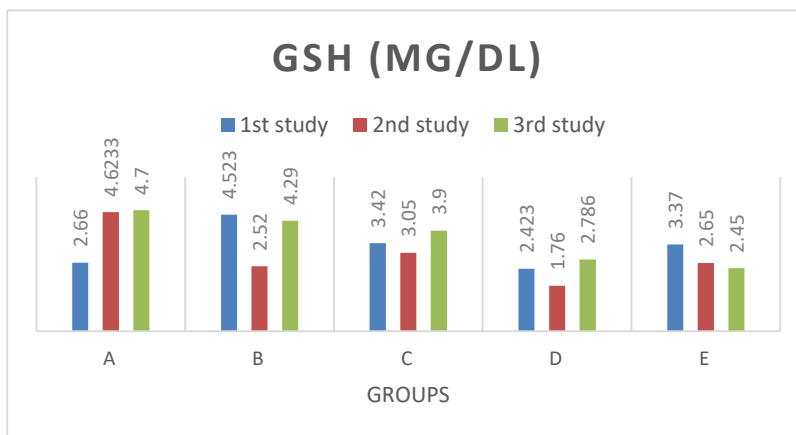


Figure 8: Shows GSH test results across groups. The GSH values for the baseline study, the post induction study (2nd study) and post treatment study (3rd study) were distinguished. GSH values continuously decreased in lead only group (group E), while there was notable increase in GSH values of treatment groups. There was significant difference ($P > 0.05$) in GSH post treatment values when compared with results of the baseline studies across group.

Histomorphological analysis

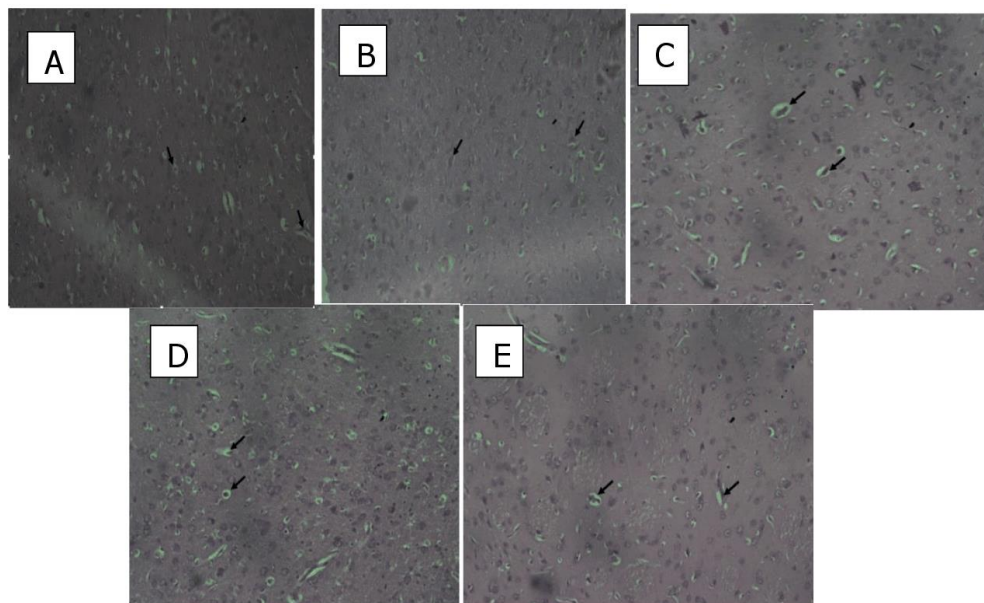


Figure 9; Sections of temporal cortices: (A) control rat (normal saline only) neuronal cells (arrow). cytoarchitecture appears normal. (B). Lead and Pyridoxine treated the cytoarchitecture appears normal with neuronal cells (arrow) (C) Lead and Vitamin C the cytoarchitecture appears normal with neuronal cells (arrow) (D) Lead and quercetin treated the cytoarchitecture appears normal with neuronal cells (arrow) (E) Lead only distortion of the cytoarchitecture (arrow) with mild glial cell infiltration. H&E. x200.

Discussion

Lead poisoning is known to cause iron deficiency which in turn is a strong contributing factor in the etiology of anemia (Staudinger & Roth, 1998). Anemia is classified as macrocytic, normocytic, or microcytic based on the size of red blood cells and the amount of hemoglobin (Sarma, 1990). A low level of hemoglobin reflects reduced PCV value, which is defined as the ratio of the RBC volume to the total blood volume (Beutler & Waalen, 2003). Additionally, anemia can be hypochromic when the MCHC value is low. In this study, lead toxicity was evident owing to the slightly decreased PCV and RBC values (Fig 1 & 3) across treatment groups. This is consistent with the findings of Mahdi *et al.*, (2013) in a clinical study on lead-exposed workers. Also, WBC, HB, and Platelets count greatly decreased after induction of lead across all treatment groups (Fig 2, 4 & 5). This is consistent with the findings of previous studies (Omotayo *et al.*, 2022; Mahdi *et al.*, 2013; Nabil *et al.*, 2012; Mugahi *et al.*, 2003).

Vitamin C was also observed to show curative effects by increasing PCV, RBC, WBC, HB and Platelets count after observed reduction by lead

administration. This was attributed to its functional ability to donate reducing equivalents to prevent the formation of reactive oxygen that damage the RBC. This finding is in line with Ozor, (2020). In another study, ascorbic acid demonstrated a substantial rise in RBC, and WBC in ascorbic acid therapy (Masar *et al.*, 2021). Pyridoxine also exhibited a similar effect as vitamin C on the PCV, RBC, WBC, HB, and Platelets counts. This is in line with the findings of Boleslaw *et al.*, (2019). Quercetin enhanced all the blood parameters evaluated: PCV, RBC, WBC, HB, and platelets count. This is suggestive of haematopoietic enhancing property and affirms reports supporting quercetin supplementation enhanced RBC, WBC HB, PCV and Platelets count (Yahaya *et al.*, 2020; Kasmi *et al.*, 2018; Keskin *et al.*, 2016; Selvakumar *et al.*, 2013; Mahmoud *et al.*, 2013).

Antioxidants play a vital role in mitigating the effect of oxidative stress on tissues and observations in this study showed SOD values after induction of lead were reduced but not significant across groups. Other studies have earlier reported similar outcomes (Jin *et al.*, 2006; Ahmed *et al.*, 2008). However, significant increases in SOD activity has been reported in lead-exposed workers (Kasperczyk *et al.*, 2009; Rendon-Ramirez *et al.*, 2014). Lead toxicity level is evident as an increased level of MDA recorded in this study. Thus is consistent with several studies which found MDA levels to be significantly higher in lead-exposed groups (Tenchova *et al.*, 1997; Ye *et al.*, 1999, Yucebilgiç *et al.*, 2003, Gurer-Orhan *et al.*, 2004, Kasperczyk *et al.*, 2013, Oktem *et al.* 2004, Patil *et al.*, 2006; Garçon *et al.*, 2007; Ergurhan-Ilhan *et al.*, 2008; Khan *et al.*, 2008, Mohammad *et al.*, 2008, Grover *et al.*, 2010, Permpongpaiboon *et al.*, 2011; Singh *et al.*, 2013). Further findings from this study also showed a significant decrease in GSH values on exposure to lead and several studies also identified a reduction in GSH levels in lead-exposed group (Mohammad *et al.*, 2008; Feksa *et al.*, 2012; Kasperczyk *et al.*, 2013). However, few studies identified increased GSH levels in lead exposed group (Gurer-Orhan *et al.*, 2004; Conterato *et al.*, 2013).

Evident from our findings quercetin considerably reduced MDA levels and increased SOD and GSH levels, thereby reaffirming its already described antioxidant properties (Yagmurca *et al.*, 2015) and confirming the protective properties of Quercetin via the regulation of antioxidant and lipid peroxidation entities (Polat *et al.*, 2006; Ikizler *et al.*, (2017). Vitamin C reduced lead-induced oxidative stress by decreasing MDA levels while increasing SOD and GSH levels. Vitamin C has the tendency to ameliorate oxidative stress levels (Bailey *et al.*, 2011; Ozor, 2021). Vollaard *et al.*, (2005) also posited that Vitamin C supplementation decreased serum MDA in exercise-induced oxidative stress. Pyridoxine also improved antioxidant markers. Pyridoxine supplementation exerted antioxidant and lipid profiles of lead-induced neurotoxicity (Tas *et al.*, 2017).

Histological observations revealed normal cytoarchitecture of the temporal cortices of the treated groups but not lead which revealed mild glial infiltrations. This was attributed to the lead effect on the cortex. Lead acetate caused mild histomorphological alterations in the brain (Jarrar *et al.*, 2012) and dose- dependant cellular degenerative changes (Highab *et al.*, 2018). Thus, lead exhibited a neurotoxic effect while the treatment quercetin, vitamin C, and pyridoxine exerted neuroprotective potential. This result was consistent with previous studies which reported the protective and antioxidant roles of quercetin, vitamin C, and pyridoxine (Vollard *et al.*, 2005; Ikizler *et al.*, 2017; Amanda *et al.*, 2019; Ozor, 2021). Quercetin, particularly, enhances the survival of neuronal cells in the cerebral cortex (Khan *et al.*, 2018).

Conclusion

Lead-induced oxidative stress consequently altered hematological parameters and temporal cerebral microstructure. The treatments with quercetin, ascorbic acid, and pyridoxine mitigated the adverse effect of lead via hematopoietic, antioxidant, and neuroprotective mechanisms.

Conflict of Interest

The authors declared that the research was conducted in the absence of any commercial or financial relationship that could be construed as a potential conflict of interest.

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We thank the staff of the histology laboratory for providing the technical assistance.

Author Contributions

FBE: conception and design and supervised the research; MEC: wrote the draft; assembled and analyzed the histology; NIS and VU: performed the study, contributed to the discussion, reviewed; OII: review literature and edited the draft. All authors read and approved the manuscript.

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Acid Hydrolysis of Cassava Peel Waste for Ethanol Production

Ifeoma E. Madukasi

Abstract

Alternative substrates for ethanol production other than food crops will definitely lead to enhancement of farmer's income and lead to food security. Cassava peel waste (CPW) rich in starch content was utilized in ethanol production. The cassava peel was collected from cassava tuber processors, milled (0.027mm) hydrolysed with 20% H₂SO₄ prior to fermentation with 5% baker's yeast for 3 – 5 days. The fermented broth was distilled using distillation apparatus. Chemical properties of the distillate identified hydroxyl ion as its functional group while physical characterization of the distillate showed ethanol yield to be 33.74g/cm³. The odour compares favourably with absolute and industrial ethanol respectively.

Keywords: cassava peel waste, ethanol production, acid hydrolysis, solid waste management

1. Introduction

Globally, ethanol production has been mainly from food crops such as corn, sugarcane, potatoes and cassava tubers [1]. These are essential crops in Africa and Nigeria in particular as they are staple and economic food crops. However, the demand for ethanol production is on the increase in recent times due to its wide use in chemical and transportation industries and also because of its role in green house gas emission reduction [2]. Although Nigeria is one of the highest cassava producers and processors in the world, the abundant waste that accrues from cassava processing is yet to be adequately tapped. In Nigeria, cassava wastes are mainly left to rot away or burnt off to create space for the accumulation of new generation of waste heaps, emitting carbon dioxide and producing a strong offensive smell [3], [4].

Cassava peel waste (CPW) is high in cyanogenic glucosides and the pomace also high in biodegradable organic matters and may cause surface water pollution especially if they are stored under heavy rain or simply disposed of in surface waters [5]. This is typical scenario in Nigeria. The price of cassava has recently increased due to high demand of the tubers as it is now mandatory in Nigeria to include 10% to 20% high quality cassava flour (HQCF) into bread and confectionaries. This has seriously affected the availability of cassava tubers as numerous cassava food derivatives abound. It is also expected that the policy on 10% to 20% inclusion of HQCF into bread and confectionaries will spur more cassava growers consequently leading to more waste from cassava

processing. Unattended wastes invariably will breed unhealthy environment which can hinder the sustainability of the production and processing process.

Cassava processing produces large amounts of waste and is generally considered to contribute significantly to environmental pollution [6]. Thus, an attribute of global warming induced climate change. Generally, the long-term and broad-based impact of cassava processing on the environment can be corrected by proper cassava waste management [7], [6] which includes the use of cassava by-products as feedstuffs or as an alternative substrate for biotechnological processes which includes alcohol production thereby alleviating environmental issues [5].

Development of proper waste management for cassava waste is very important as it will solve many environmental challenges as well as alleviate poverty, and enhance the incomes of both urban and rural farmers. It will also enable the nation to meet the Millennium Development Goals (MDG) on environmental sustainability [8], [9]. Utilization of cassava peel waste for ethanol production is a carbon neutral process which will not affect the teeming populace that depends on cassava as food sources; rather, it will close the loop in cassava processing in Nigeria.

Cassava flour has potentials for alcohol production due to its high content of fermentable sugar and stable shelf-life [10], [11] and also because of its complete and easier hydrolysis compared to other flours [9]. However, for its use in ethanol production, acids or cellulose enzymes catalyze the breakdown of cellulose into glucose, which are fermented to ethanol [12]. Enzyme hydrolysis for the production of ethanol from starchy materials is an expensive process [13]. Chemical hydrolysis gives advantages for short residence time than enzyme hydrolysis [14].

Basically, two different processes can be used to produce ethanol from starchy crops: dry milling and wet milling processes. In dry milling, the feed material is ground mechanically and cooked in water to gelatinize the starch. The enzymes or acids are then added to break down the starch to form glucose, which yeast ferments to ethanol. The separate hydrolysis and fermentation process uses distinct process steps for starch hydrolysis and glucose fermentation. The primary advantage of this process is that hydrolysis and sugar fermentation can be treated separately, thus minimizing the interaction between these steps [12].

Utilization of cassava flour in ethanol production will add to food insecurity, hence the proposed utilization of agro-waste rich in starch and cellulosic matter. The aim of this work is to produce bio-ethanol from cassava peel waste and other agro-waste materials that are high in starch and cellulosic matters through acid hydrolysis and fermentation processes.

2. MATERIALS AND METHODS

2.1. Materials: The CPW was collected from FIIRO pilot garri processing plant, dried, milled with hammer milling machine (0.027mm).



Fig 1: FIIRO CASSAVA PROCESSING LINE



2.2. Pretreatment: Dry milling process was used before acid activation, this step enhanced visibility of the pores of the CPW for easier acid hydrolysis. In this method, the sieved CPW was boiled in water with constant stirring to a temperature of 70°C until the CPW gelatinized.

2.3. Acid Hydrolysis To the gelatinized sample, the prepared solution of the sulfuric acid was added with constant stirring until a homogenous mixture was formed. The solution was heated with constant stirring on a magnetic stirring hotplate until temperature of 65°C was reached. At this point, the texture and color of the solution changed. This was allowed to cool, filtered through No.1 whatman filter paper and the pH was adjusted to 4.5 with 0.1M NaOH.

2.4. Fermentation The CPW hydrolysate was fermented in an aspirator bottle (previously sterilized to exclude other microorganisms) with the baker's yeast. The bottle was topped with straw to allow carbon dioxide to escape. Fermentation was done for 3 days and 5 days at room temperature. At the end of the fermentation period, the alcohol was separated from the extract using simple distillation.

2.5. Distillation process The distillation apparatus consisted of conical flask, condenser, splash head (to avoid the entrance of water vapors into the receiver) and the receiver. The fermented CPW hydrolysate was added into the conical flask and the set up was heated with a heating mantle at temperature between 75-80°C. The distillate collected was allowed to cool and the density was obtained.

2.6. Determination of Percentage Ethanol Concentration A slight modification of method according to [15] was used. Series of percentage (V/V) ethanol water solution were prepared and were weighed. The density of each of the prepared ethanol solution was calculated and a standard curve of density against percentage ethanol was plotted. The distillate was weighed and its density calculated. The percentage ethanol concentration of ethanol produced was obtained by comparing its density with the standard ethanol density curve.

2.7. Methodology: The sample was dried, milled with hammer milling machine (0.027mm), cooked in a pressure pot for 30 minutes prior to addition of 20% (18molar) sulphuric acid. The mixture was stood for 48hr and 5% baker's yeast added into the content after pH adjustment to optimum condition of pH5.5. The mixture was agitated and 72hr to 96hr was allowed for complete fermentation. The liquor was filtered and the filtrate distilled using distillation apparatus. The process flow chart is as shown in Fig. 2.

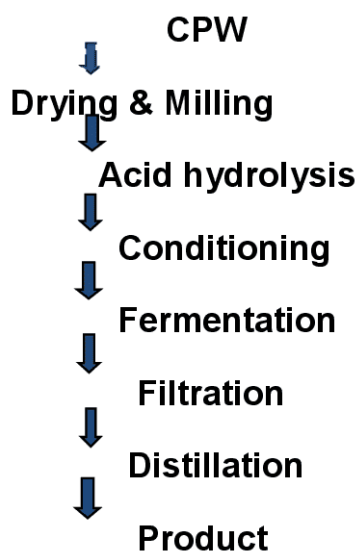


Fig. 2: Process flowchart of ethanol production from cassava peel waste

3. Results and Discussion:

Table 1: Evaluation of Product Recovered From Preliminary Investigation

Investigations	Volume Recovered (ml/100g)	Quantity Produced	pH Values
Sample A	42ml	33.74g/cm ³	5.74
Sample B	41ml	32.94g/cm ³	4.55
Sample C	76ml	61.05g/cm ³	4.01
Sample D	15ml	12.05g/cm ³	7.54
Sample E	69ml	55.43g/cm ³	7.97

N/B: Density and pH of absolute ethanol= 0.8033g/cm³ and 7.00

Table 2: Determination of Physical & Chemical Properties of Ethanol Produced from CPW

Sample	pH	Density	Refractive Index	Solubility	Functional Group (OH ⁻)
Absolute Ethanol	7.00	0.78	-	Positive	Positive
CPW A	5.74	0.9743	1.3405	Positive	Positive
CPW B	4.55	0.9757	1.3407	Positive	Positive
CPW C	4.01	0.9769	1.3313	Positive	Positive
CPW D	7.54	0.9309	1.334	Positive	Positive
CPW E	7.94	0.9943	1.3309	Positive	Positive

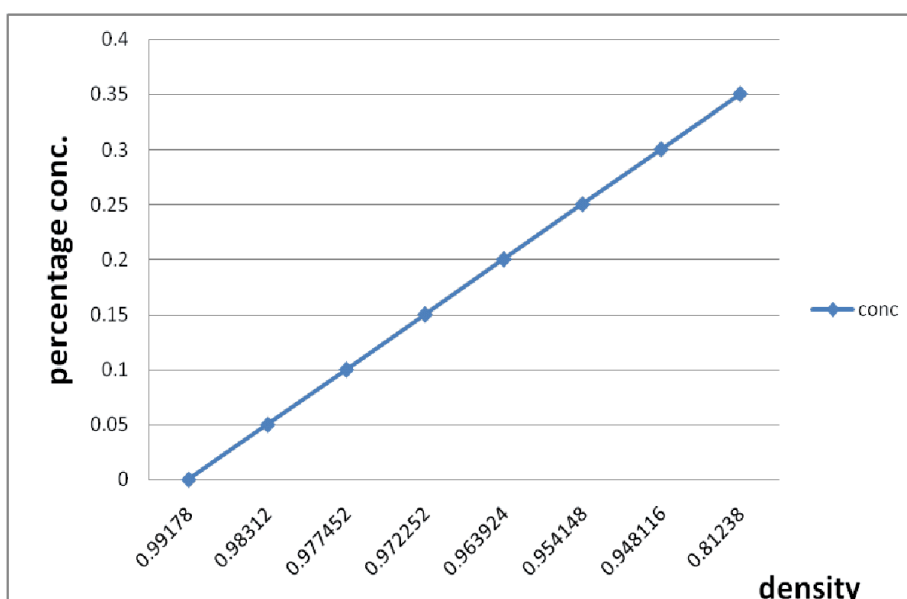


Fig 3: Determination of Ethanol Concentration

The distillate collected was measured with a measuring cylinder and expressed as quantity of ethanol produced in g/l by multiplying the volume yield of the distillate by ethanol density. From the trial investigations as shown in Table 1 above, CPW ethanol yield is comparable with literature value of 40% and above as recorded by [13]. The CPW yield was in the range of 33 – 60g/cm³ for the sterilized hydrolysate and 15-28g/cm³ for the non-sterilized hydrolysate. This is an indication that the baker's yeast would have competed with other micro-organisms that hindered its activity otherwise depleted the available sugar in the case of non-sterilized hydrolysate. Table 2 shows the physical and chemical properties of ethanol as to ascertain the strength level and its degree of purity as compared to standard (absolute ethanol).

In addition, CPW granules were extracted by crushing and pressure cooking to gelatinize the starchy content which was then treated with acid at 50 – 60 degree Celsius for 30 minutes to convert the starchy content into sugar (maltose). Addition of yeast in adequate proportion at room temperature converted the maltose to glucose with the aid of maltase while zymase also found in yeast decomposed glucose to ethanol with evolution of carbon dioxide. In summary, acid hydrolysis of carbohydrate to sugar is favoured in that it is faster with shorter residence time than enzyme hydrolysis.

4. CONCLUSION

In summary, acid hydrolysis of carbohydrate to sugar is favoured in that it is faster with shorter residence time in ethanol production. The use of cassava peel waste in ethanol production has shown that cassava has a holistic value and if properly harnessed will improve the economic values of the cassava growers in Nigeria. In addition, the work indicates that proper waste management is a tool to wealth creation and resource recovery.

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Null Controllability of Semi-Linear Differential Systems of NonLocal Initial Conditions with Distributed Delays in the Control in Banach Spaces

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ABSTRACT

In this work, a Semi linear Differential System of Non Local Initial Conditions with Distributed Delays in the Control in Banach spaces of the form

$$x^1(t) = Ax(t) + f(t, x(t)) + \int_{-h}^0 [d_\theta H(t, \theta)] u(t + \theta)$$

$$x(0) + g(x) = x_0$$

is presented for controllability analysis. Necessary and Sufficient Conditions for the System to be null controllable are established. Use is made of the Unsymmetric Fubini theorem and Schauders' fixed point theorem to establish results. Conditions are also placed on the perturbation f which guarantee that if the linear control base system is proper and if the uncontrolled linear system is uniformly asymptotically stable, then the Semilinear Differential System is nullcontrollable with constraints.

Keywords: null-controllability, semi-linear, distributed delays, nonlocal initial conditions, Banach spaces

1. INTRODUCTION

Controllability and Null Controllability of nonlinear systems represented by differential and Integrodifferential equations in Banach Spaces have been investigated extensively by many authors; **Balachandran, K. Anandhi (2004), Y.K.Chang, J.J. Nieto(2009), Oraekie,P.A(2017)**.A method is to transform the controllability problem into a fixed point problem for an appropriate operator in a function space. However, **Balachandran and Kim(2003)** pointed out that controllability results are only true for ordinary differential Systems in finite-dimensional spaces if the corresponding operator semi groups are

compact. **Xue, X (2008)** studied the existence of integral solutions for a nonlinear differential equations with nonlocal initial conditions through Hausdorff measure of no compactness in the separable and uniformly smooth Banach spaces. In his work, **Xue, X (2008)** dropped the compactness of semi group. The semi group in his work is a contraction semi group satisfying equicontinuity, which is a special case of a strongly continuous semigroup. With respect to controllability, it is known from the of **Hermes and J.P. La Salle (1969)** that if the linear ordinary control system

$$\dot{x}(t) = A(t)x(t) + B(t)u(t) \tag{1}$$

Is proper and if the free system

$$\dot{x}(t) = A(t)x(t) \tag{2}$$

Is uniformly asymptotically stable, then system (1) is null controllable with constraints. A similar result was obtained by **Chukwu (1980)** for the delay system of the form

$$\dot{x}(t) = L(t, x_t) + B(t)u(t) + f(t, x_t, u(t)) \tag{3}$$

where, $L(t, \phi) = \sum_{k=0}^{\infty} A_k(t)\phi(-t_k) + \int_{-r}^0 A(t, s)\phi(s)ds.$

Shinba (1985) studied the nonlinear infinite delay system of the form

$$\dot{x}(t) = L(t, x_t) + B(t)u(t) + \int_{-\infty}^0 A(\theta)x(\theta)d\theta + f(t, x_t, u(t)) \tag{4}$$

And showed that system (4) is Euclidean null controllable if the linear base system

$$\dot{x}(t) = L(t, x_t) + B(t)u(t) \tag{5}$$

Is proper and the free system

$$\dot{x}(t) = L(t, x_t) + B(t)u(t) + \int_{-\infty}^0 A(\theta)x(\theta)d\theta \tag{6}$$

is uniformly asymptotically stable, provided that f satisfies some growth conditions.

Onwuatu (1993), studied the neutral systems with infinite delay of the form

$$\frac{d}{dt}D(t, x_t) = L(t, x_t) + B(t)u(t) + \int_{-\infty}^0 A(\theta)x(t + \theta)d\theta + f(t, x_t, u(t)) \tag{7}$$

$x(t) = \phi(t); t \in (-\infty, 0]$

where, $L(t, \phi) = \sum_{k=0}^{\infty} A_k(t)\phi(-t_k) + \int_{-r}^0 A(t, s)\phi(s)ds.$

He developed sufficient computable criteria for the null controllability of system (7).

While **Oraekie (2018)** studied the nonlinear infinite neutral systems with Multiple Delays in the Control of the form:

$$\frac{d}{dt}D(t, x_t) = L(t, x_t) + \sum_{j=1}^m B_j u(t - h_j) + \int_{-\infty}^0 A(\theta)x(t + \theta) d\theta + f(t, x_t, u(t)) \dots \dots \tag{8}$$

He developed sufficient computable criteria for the null controllability of the system (8).

*His results extend those of **Hermes and Salle (1969)**, **Chukwu (1980)**, **Sinba (1985)** and **Onwuatu (1993)** to nonlinear infinite neutral systems with multiple delays in the control.*

In this paper, therefore, we consider the null controllability of the Semilinear Differential Systems of Nonlocal Initial Conditions with Distributed Delays in the Control in Banach Spaces of the form:

$$x^1(t) = Ax(t) + \int_{-h}^0 [d_\theta H(t, \theta)] u(t + \theta) + f(t, x(t)) \tag{9}$$

$$x(0) + g(x) = x_0$$

with the main objective of investigating the null controllability of the system(8).

Here, the state $x(\cdot)$ takes value in a Banach Space $X = R^n$ with the norm $|\cdot|$;

the operator A generates a strong continuous not necessarily compact, semigroup $T(t)$ in X .

And the control function $u(\cdot)$ is given Lebsgue square integrable functions $L_2(J, U)$;

there is a Banach Space of admissible control functions with U a Banach Space. $H(t, \theta)$ is an

$n \times n$ matrix function continuous at t and of bounded variation in θ on $[-h, 0]$, $h > 0$

for each $t \in [t_0, t_1]$; $t_1 > t_0$.

The functions $f: J \times X \rightarrow X$, $g: C(J, X) \rightarrow X$ are continuous. Here, $x_0 = x(0)$ is a given

element in X , $C(J, X)$ denotes the Banach space of continuous functions $x(\cdot) : J \rightarrow X$

with the norm $\|x\| = \sup\{|x(t)|, t \in J\}$.

The nonlocal initial condition is a generalization of the classical initial condition, which

was motivated by physical phenomena. The pioneering work on nonlocal conditions is due to

Byszewski (1991) followed by **Fu. X. Ezzinbi(2003)**.

2. Preliminaries and Notations

Consider the following dynamical system(9) given as

$$\begin{aligned} x^1(t) &= Ax(t) + \int_{-h}^0 [d_\theta H(t, \theta)] u(t + \theta) + f(t, x(t)) \\ x(0) + g(x) &= x_0 \end{aligned} \quad (11)$$

If $T(t, t_0): B \rightarrow B$, $t > t_0$ is defined by $T(t, t_0)\phi = x_t(t_0, \phi)$ and the solution $x(t)$ of

system(11) with the initial complete state $y_{t_0} = \{x_0, u_0\}$ is of the following form

(see **Klamka(1978)** as contained in **Klamka(1980)**):

$$\begin{aligned} x(t) &= T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds \\ &+ \int_{t_0}^t T(t-s) \int_{-h}^0 [d_\theta H(t, \theta)] u(t + \theta)ds \end{aligned} \quad (12)$$

Where $T(t-s)$ is the state transition of the following linear homogeneous system

$$x^1(t) = Ax(t) \quad (13)$$

The third term in the right – hand side of system(12) contains the values of the control $u(t)$ for $t < t_0$, as well as for $t > t_0$. The values of the control $u(t)$ for $t \in [t_0 - h, t_0]$ enter into the definition of initial complete state y_{t_0} . To separate them, the third term of

system(12) must be transformed by changing the order of integration..Using the Unsymmetric Fubini theorem, we have the following equalities:

$$x(t) = T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0}^t T(t-s)H(l, \theta)u(l+\theta)dl \right) \quad (14)$$

$$\Rightarrow x(t) = T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t+\theta} T(t-s)H(l-\theta, \theta)u(l-\theta+\theta)dl \right) \quad (15)$$

$$= T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t+\theta} T(t-s)H(l-\theta, \theta)u(l)dl \right) \quad (16)$$

$$\Rightarrow x(t) = T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t-s)H(l-\theta, \theta)u_{t_0}(l)dl \right) + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0}^{t+\theta} T(t-s)H(l-\theta, \theta)u(l)dl \right) \quad (17)$$

Where the symbol d_{H_θ} denotes that the integration is in the Lebesgue – Sieltjes senes with respect to the variable θ in the function $H(l, \theta)$.

Let us introduce the following notation

$$H_t(l, \theta) = \begin{cases} H(l, \theta), & l < t, \theta \in R \\ 0, & l > t, \theta \in R \end{cases} \quad (18)$$

Thus, $x(t)$ can be expressed in the following form:

$$\Rightarrow x(t) = T(t)[x_0 - g(x)] + \int_{t_0}^t T(t-s)f(s, x(s))ds$$

$$\begin{aligned}
 & + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t-s) H(l-\theta, \theta) u_{t_0}(l) dl \right) \\
 & + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0}^t T(t-s) H_t(l-\theta, \theta) u(l) dl \right) \tag{19}
 \end{aligned}$$

Using again the Unsymmetric Fubini theorem, the equality (19) can be rewritten in a more convenient form as follows:

$$\begin{aligned}
 x(t) = T(t)[x_0 - g(x)] & + \int_{t_0}^t T(t-s) f(s, x(s)) ds \\
 & + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t-s) H(l-\theta, \theta) u_{t_0}(l) dl \right) \\
 & + \int_{t_0}^t \left(\int_{-h}^0 T(t-s) d_\theta H_t(l-\theta, \theta) \right) u(l) dl \tag{20}
 \end{aligned}$$

Now let us consider the system (20) – the exact mild solution of the system(8) for $t = t_1$

$$\begin{aligned}
 x(t_1) = T(t_1)[x_0 - g(x)] & + \int_{t_0}^{t_1} T(t_1-s) f(s, x(s)) ds \\
 & + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1-s) H(l-\theta, \theta) u_{t_0}(l) dl \right) \\
 & + \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1-s) d_\theta H_{t_1}(l-\theta, \theta) \right) u(l) dl \tag{21}
 \end{aligned}$$

2.1 BASIC SET FUNCTION AND PROPERTIES.

Definition 2.1.1 (Reachable Set)

The reachable set of the system(9) denoted by $R(t_1, t_0)$ is given as:

$$R(t_1, t_0) = \left\{ \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1-s) d_\theta H_{t_1}(l-\theta, \theta) \right) u(l) dl : u \in U; |u_j| \leq 1; j = 1, 2, \dots, m \right\}$$

where $U = \{u \in L_2([t_0, t_1], R^m)\}$.

Definition 2.1.2 (Target Set)

The target set for the system(9) denoted by $G(t_1, t_0)$ is given as:

$$G(t_1, t_0) = \{x(t_1, x_0, u) : t_1 \geq \tau > t_0, \text{ for some fixed } \tau \in [t_0, t_1] \text{ and } u \in U\}.$$

Definition 2.1.3 (Attainable Set)

The attainable set for the system(9) denoted by $A(t_1, t_0)$ is given as:

$$A(t_1, t_0) = \{x(t_1, x_0, u) : u \in U ; |u_j| \leq 1 ; j = 1, 2, \dots, m \}; U = \{u \in L_2([t_0, t_1], R^m)\}.$$

Definition2.1.4 (Controllability Grammian or Map)

The controllability grammian or map of the system(9)denoted by $W(t_1, t_0)$ is given as

$$W(t_1, t_0) = \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right)^T$$

Where T denotes matrix transpose.

$$\text{If } Y(t_1) = \int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \tag{22}$$

$$\text{Then, } W(t_1, t_0) = \int_{t_0}^{t_1} Y(t_1) Y^T(t_1) \text{ and } W^{-1}(t_1, t_0) = \frac{\mathbf{1}}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \tag{23}$$

Definition2.1.5 (Properness)

The system (9)is said to be proper on an interval $[t_0, t_1]$ if

$$C^T \int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) = 0 \text{ ae, } l \in [t_0, t_1] \Rightarrow C = 0; C \in R^n.$$

If the system(9)is proper on each interval $[t_0, t_1]; t_1 > t_0$, we say that system(9) is proper in R^n .

Definition2.1.6 (Positive Definite)

The controllability grammian or map of the system(9)denoted by $W(t_1, t_0)$ is said to be positive definite if $W(t_1, t_0)$ varnishes only at the origin and $W(x) > 0$, for all $x \neq 0; x \in D$, where $D = \{x \in R^n : \|x\| \leq r ; r > 0\} \subset R^n$.

Definition2.1.7 (Complete Controllability)

The system(9) is said to be completely controllable on the interval $[t_0, t_1]$ if for every function ϕ and every state $x_1 \in R^n$, there exists an admissible control energy function $u \in U$ such that $x(t_1) = x_1$.

Definition2.1.8 (Complete State)

We denote the complete state of system(9) by $z(t) = \{x(t), u_t\}$

Then, the initial complete state of system(9) at time t_0 is $z(t_0) = \{x(t_0), u_{t_0}\}$

Definition2.1.9 (Null Controllability)

The system(9) is said to be null controllable on the interval $[t_0, t_1]$ if for every function $\phi \in B([t_0, t_1], R^n)$, there exists a time $t_1 \geq t_0, u \in L_2([t_0, t_1], P), P$ a compact convex subset of R^m such that the solution $x(t, t_0, \phi, f)$ of system(9) satisfies

$$x_{t_0}(t_0, \phi, f) = \phi \text{ and } x(t_1, t_0, \phi, f) = 0$$

Definition2.1.10 (Relative Controllability)

The system(9) is said to be relatively controllable on the interval $[t_0, t_1]$ if

$$A(t_1, t_0) \cap G(t_1, t_0) \neq \phi, \quad t_1 > t_0 \in [t_0, t_1].$$

3. MAIN WORK

The following theorems on controllability of system(9) are similar to the corresponding results for linear control systems of various types including some with delays and some without delays(see **Oraekie(2017),Onwuatu(1993),Hermes and La Salle(1963)**).

Theorem 3.1

The following statements are equivalent:

- (i) The controllability grammian $W(t_1, t_0)$ of sysem(9)is non – singular
- (ii). System(9) is completely controllable on the interval $[t_0, t_1]. t_1 > t_0$
- (iii). System(9) is proper on the interval $[t_0, t_1]. t_1 > t_0$

Proof

The controllability grammian $W(t_1, t_0)$ of sysem(9)is nonsingular is equivalent to saying that it is positive definite, which in turn is equivalent to saying that the C^T of the controllability index of system(9)is equal to zero almost everywhere , implies that $C = 0$.

$$i.e . C^T \int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) = 0 \text{ a e } , l \in [t_0, t_1] \Rightarrow C = 0; C \in R^n. \text{ Thus, showing that (i) and (iii) are equivalent..}$$

Now consider

$$C^T \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) u(l) dl = 0 \text{ a e } , l \in [t_0, t_1].$$

For each l , then

$$\int_{t_0}^{t_1} C^T \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) u(l) dl = C^T \left[\int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) u(l) dl \right] = \mathbf{0}$$

It follows from this that C is orthogonal to the reachable set $\mathbf{R}(t_1, t_0)$.

If we assume the relative controllability of system(9) now, then

$\mathbf{R}(t_1, t_0) = R^n$, so that $C = 0$. Showing that (ii) implies (iii).

Conversely, assume that system(9) is not controllable so that

$$\mathbf{R}(t_1, t_0) = R^n, t_1 > t_0 .$$

Then there exists $C \neq 0, C \in R^n$ such that

$$C^T \mathbf{R}(t_1, t_0) = 0$$

It follows now that for all admissible controls $u \in U \subset L_2([t_0, t_1], R^n)$

$$0 = C^T \left[\int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) u(l) dl \right]$$

$$\text{Hence, } C^T \mathbf{R}(t_1, t_0) = 0 \text{ a e } , l \in [t_0, t_1], C \neq 0.$$

This situation, implies that system(9) is not proper by the definition of properness since

$C \neq 0$. Hence, the system(9) is relatively controllable on $[t_0, t_1]$ and hence completely controllable.

Theorem 3.2

Assume for system (9) that:

(i). the constraint set U is an arbitrary compact subset of R^n .

(ii). the system(6) satisfies exponential estimate.

$$i.e. \|x(t, t_0, \phi, 0)\| \leq M e^{-\delta(t-t_0)} \|\phi\|, \quad \text{for some } \delta > 0, M > 0.$$

(iii). the linear control system – (system(5)), is proper in R^n .

(iv). the continuous function f satisfies

$$|f(t, x(\cdot), u(\cdot))| \leq \exp(-Nt) \pi(x(\cdot), u(\cdot)), \text{ for all } (t, x(\cdot), u(\cdot)) \in [t_0, \infty) \times \text{Ex}L_2,$$

where $\int_{t_0}^{\infty} \pi(x(s), u(s)) ds \leq \lambda < \infty$ and $N - \delta \geq 0$, then system(9) is null controllable.

Proof

By (iii) – the linear base control system (system(5)), there exists an inverse of the controllability grammian say $W^{-1}(t_1, t_0)$ for each time $t_1 > t_0$. Suppose that the pair of functions x and u form a solution pair to the set of integral equations:

$$u(t) = - \left[\int_{-h}^0 T(t_1 - s) d_{\theta} H_{t_1}(l - \theta, \theta) \right]^T W^{-1}(t_1, t_0) \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s) f(s, x(s)) ds + \int_{-h}^0 d_{H_{\theta}} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \right]$$

Substituting equation (22) and (23) into the above, we have

$$u(t) = \frac{-Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s) f(s, x(s)) ds + \int_{-h}^0 d_{H_{\theta}} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \right] \tag{24}$$

$$x(t) = T(t)[x_0 - g(x)] + \int_{t_0}^t T(t - s) f(s, x(s)) ds + \int_{-h}^0 d_{H_{\theta}} \left(\int_{t_0+\theta}^{t_0} T(t - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) + \int_{t_0}^t \left(\int_{-h}^0 T(t - s) d_{\theta} H_t(l - \theta, \theta) \right) u(l) dl \tag{25}$$

$$x(t) = \phi(t), t \in [t_0 - \lambda, t_0].$$

Then u is square integrable on $[t_0, t_1]$ and x is a solution of system(9) corresponding to u with the initial state $x(t_0) = \phi$.

Also, using u as expressed in equation (24), we have

$$\begin{aligned} x(t_1) = & T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \\ & + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \\ & + \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta) \right) \frac{-Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \right. \\ & \left. + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \right] \end{aligned} \quad (26)$$

But $Y(t_1) = \int_{-h}^0 T(t_1 - s) d_{\theta}H_{t_1}(l - \theta, \theta)$, therefore, we have

$$\begin{aligned} x(t_1) = & T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \\ & + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \\ & + \int_{t_0}^{t_1} (Y(t_1)) \left(\frac{-Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \right) \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \right. \\ & \left. + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \right] \end{aligned} \quad (27)$$

$$\begin{aligned} \Rightarrow x(t_1) = & T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \\ & + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \\ & - \left(\frac{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \right) \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds \right. \\ & \left. + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta)u_{t_0}(l)dl \right) \right] \end{aligned} \quad (28)$$

$$\Rightarrow x(t_1) = T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds$$

$$\begin{aligned}
 & + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \\
 - \mathbf{1} & \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s) f(s, x(s)) ds \right. \\
 & \left. + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \right] \tag{29}
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow x(t_1) & = T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s) f(s, x(s)) ds \\
 & + \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \\
 & - [T(t_1)(x_0 - g(x))] - \int_{t_0}^{t_1} T(t_1 - s) f(s, x(s)) ds \\
 & - \int_{-h}^0 d_{H\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) = 0 .
 \end{aligned}$$

It remains to show that the function $u: [t_0, t_1] \rightarrow U$ is an admissible control. That is, we need to show that $u: [t_0, t_1] \rightarrow U$ is in the arbitrary compact constraint subset of R^m . That is $|u| \leq \delta_1$, for some constant $\delta_1 > 0$. By (ii) of theorem 3.2, we have

$$\begin{aligned}
 & \left| \left[\int_{-h}^0 T(t_1 - s) d_{\theta} H_{t_1}(l - \theta, \theta) \right]^T W^{-1}(t_1, t_0) \right| < \lambda_1 \\
 \text{i.e. ; } & \left| \frac{Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \right| < \lambda_1, \quad \text{for some } \lambda_1 > 0 \text{ and}
 \end{aligned}$$

$$|T(t_1)[x_0 - g(x)]| \leq \lambda_2 \exp(-\delta(t_1 - t_0)) \quad , \text{ for some constant } \lambda_2 > 0$$

Hence,

$$|u(t)| \leq \lambda_1 [\lambda_2 \exp(-\delta(t_1 - t_0))] \int_{t_0}^{t_1} \lambda_3 \exp[-\delta(t_1 - s) \exp(-Ns) \pi(x(\cdot), u(\cdot))] ds$$

Thus,

$$|u(t)| \leq \lambda_1 [\lambda_2 \exp(-\delta(t_1 - t_0))] + \lambda \lambda_3 \exp(-\delta t_1) \tag{30}$$

since $N - \delta \geq 0$ and $s \geq t_0 \geq 0$.

Hence, by taking t sufficiently large, we have

$|u(t)| \leq \delta_1$, $t \in [t_0, t_1]$, showing that u is an admissible control.

Finally, we now prove the existence of a solution pair of the integral equations(24)and(25).

Let E be the Banach space of all functions $(x, u): [t_0 - h, t_1] \times [t_0 - h, t_1] \rightarrow \mathbb{R}^n \times \mathbb{R}^m$,

where $x \in E([t_0 - h, t_1], \mathbb{R}^n)$; $u \in L_2([t_0 - h, t_1], \mathbb{R}^m)$ with the norm defined by

$$\|(x, u)\| = \|x\|_2 + \|u\|_2$$

$$\text{where, } \|x\|_2 = \sqrt{\int_{t_0-h}^{t_1} |x(s)|^2 ds}; \quad , \|u\|_2 = \sqrt{\int_{t_0-h}^{t_1} |u(s)|^2 ds}$$

We define the operator T by $T: E \rightarrow E$ by $T(x, u) = (y, v)$, where

$$v(t_1) = \frac{-Y^T(t_1)}{\int_{t_0}^{t_1} Y(t_1) Y^T(t_1)} \left[T(t_1)(x_0 - g(x)) + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) \right] \quad (24)$$

And $v(t) = \omega(t)$, for some $t \in [t_0 - \lambda, t_0]$

$$y(t_1) = T(t_1)[x_0 - g(x)] + \int_{t_0}^{t_1} T(t_1 - s)f(s, x(s))ds + \int_{-h}^0 d_{H_\theta} \left(\int_{t_0+\theta}^{t_0} T(t_1 - s) H(l - \theta, \theta) u_{t_0}(l) dl \right) + \int_{t_0}^{t_1} \left(\int_{-h}^0 T(t_1 - s) d_\theta H_{t_1}(l - \theta, \theta) \right) u(l) dl \quad (25)$$

$y(t) = \phi(t), t \in [t_0 - \lambda, t_0]$.

We have already shown that $|u(t)| \leq \delta_1, t \in J = [t_0, t_1]$ and also for the function

$$v: [t_0 - h, t_0] \rightarrow U,$$

we have $|v(t)| \leq \delta_1$. Hence, $\|x\|_2 \leq \delta_1(t_0 + h - t_0)^{\frac{1}{2}} = N_0$.

Again, $|y(t)| \leq \lambda_2 \exp[-\delta(t_1 - t_0)] + \lambda_4 \int_{t_0}^{t_1} |v(s)| ds + \lambda \lambda_3 \exp(-\delta t_1)$, where

$$\lambda_4 = \sup \left| \int_{-h}^0 T(t_1 - s) d_\theta H_{t_1}(l - \theta, \theta) \right|.$$

Since $\delta > 0, t_1 \geq t_0 \geq 0$, we deduce that

$$|y(t)| \leq \lambda_2 + \lambda_4 \delta(t_1 - t_0) + \lambda \lambda_3 = N_1, t \in [t_0, t_1].$$

and $|y(t)| \leq \sup|\phi| = \beta, t \in [t_0 - r, t_0]$.

Hence, if $M = \max[N_1, \beta]$, then, $\|y\|_2 \leq M(t_0 + h - t_0)^{\frac{1}{2}} = N_2 < \infty$.

Let $\rho = \max[N_0, N_2]$.

Then, if $G(\rho) = \{(x, u) \in E : \|x\|_2 \leq \rho, \|u\|_2 \leq \rho\}$, we have thus shown that the operator T maps G into its self. i.e, $T : G(\rho) \rightarrow G(\rho)$.

Since $G(\rho)$ is closed, bounded and convex, by **Riesz theorem** as contained in **Kantorovica, L. V and G. P. Akilov (1982), p297, and Oraekie(2017). Onwuatu (1993)** it is relatively compact under the transformation of T . Hence, the Schauders' fixed point theorem implies that T has a fixed point. Thus, the system(9) is null controllable.

4 .CONCLUTION

The Set Functions upon which our studies hinged are also extracted from the mild solution which we cultivated. Necessary and Sufficient Conditions for the null controllability of the Semi linear differential systems with distributed delays in the control have been derived.

These conditions are given with respect to the controllability of the linear controlled base system of system(9) and the uniformly asymptotic stability of the uncontrolled linear system of the system(9), assuming that the perturbation f satisfies some smoothness and growth conditions. These results extended known results in the literature.

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Applications of Information Cryptography in Its Various Stages of Evolution, from Antiquity to the Modern Era

Nnaemeka Uchenna Ezeonyi, Obikwelu Raphael Okonkwo & Obinna Arthur Enweka

Abstract

Communication is a daily activity. Information needs to be move from a sender to a receiver, for a communication to hold. However, there are information or messages that should be kept secret and does not require knowledge of a third party. Such messages are encrypted or coded into a cipher text, so as to make no meaning to a third party who may eventually intercept it. This coding of information is called Encryption, while Decryption is the reverse of encryption. Thus, Cryptography is the process of encryption of plain texts and decryption of cipher texts. Cryptography began in early civilizations of Hebrew, Egypt, and Rome with the Atbash, Hieroglyph and Ceaser's Ciphers respectively. This period is regarded as the "Antiquity". Cryptography later evolved into Classic Cryptography, in the Middle Ages, where the "Key Model" and "Cryptanalysis" or code-breaking were introduced. Furthermore, Cryptography evolved to "Field Ciphers" and "Tele-Printer Ciphers" during the World War I. Moreover, the World War II saw the evolution of cryptography into various "Cipher Machines". In modern times, cryptography evolved into sophisticated mathematical equations called "Algorithms", for encrypting and decrypting messages. At these various evolution stages, cryptography is seen to be applied in civil communications, wars, cryptanalysis and e-commerce.

Keywords: cryptography, cryptanalysis, ciphers, encryption, decryption, data.

1.0 Introduction

Cryptography is a method of protecting information and communications through the use of codes, so that only those for whom the information is intended can read and process it (Richards, 2021).Cryptography is one of the techniques used to ensure secure transmission of information via a channel between a pair of communicators. This prevents third parties from being acquainted with the data in transit (Peralta et al, 2014).Cryptography is a Greek word that means 'secret writing'. Cryptography is the science of both encryption and decryption.

Encryption is the process of encoding a message in such a way as to hide its contents. A plain or normal text sent over the network is converted into cipher text so that the information can only be used by the sender and the receiver (Krishna and Manikandan, 2020). The reverse process of encryption is called Decryption. It is the process of converting Cipher Text into Plain Text. Cryptographers use the decryption algorithms at the receiver side to obtain the original message from non-readable message i.e. Cipher Text (Naser, 2021). However, from ancient times till this modern times, several cryptographic techniques have been invented. This study presents cryptography in different era and are treated in the following order:

- Cryptography in the Antiquity
- Cryptography in the Middle Ages (*Classical Cryptography*)
- Cryptography in the World War I
- Cryptography in the World War II
- Modern Cryptography

2.0 Main Body

2.1 Cryptography in Antiquity

Antiquity is any period before the European Middle Ages (5th to 15th centuries) but still within the history of Western civilization ("Antiquity", 2023). According to Naser (2021), from the beginning of civilization when people started to live in different tribes or groups, each of them got the idea to be more powerful than others and to rule other tribes. So they feel for a secure and secret communication and thus how the process of primary cryptography was introduced. Hebrew scholars made use of simple mono-alphabetic substitution ciphers (such as the Atbash cipher) beginning perhaps around 600 to 500 BC ("Antiquity", 2023). Early civilizations in Egypt, Greece, and Rome adopted encryption for communication. Nearly 1900 B.C. (2000 B.C.), in ancient Egypt, a non-standard encryption was utilized on hidden "hieroglyphics" engraved on stone—the earliest known instance of cryptography—to conceal the meanings from those who did not know them, and for the amusement (Naser, 2021). By later periods of antiquity, cryptography was widely used to protect important military information, a purpose that it still serves to this day. A prominent example of Roman cryptography, known as the Caesar cipher, involved shifting the letters of an encrypted message by a certain number of places down the Latin alphabet.

Knowing this system and the number of places to shift the letters, a recipient could successfully decode the otherwise illegible message.

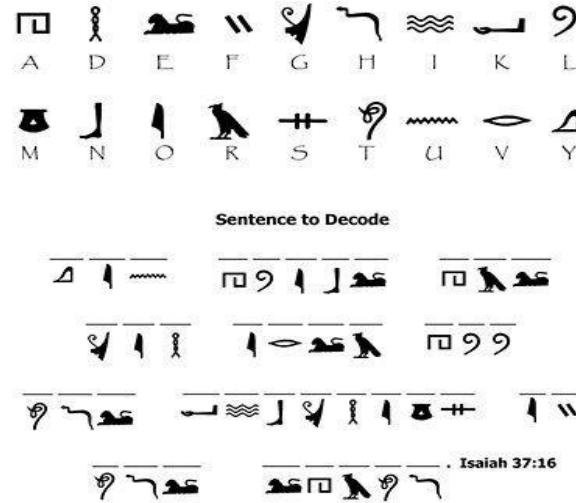


Figure 1: Hieroglyph (First techniques of Cryptography) (Hashmi and Choubey, 2018).

Below is a summary of the cryptographic techniques in Antiquity.

Period	Cryptographic Techniques		
Antiquity	(1). Atbash Cipher	(2). Hieroglyph	(3). Caesar Cipher
(5th to 15th Century)	<ul style="list-style-type: none"> • 600 – 500 BC • By Ancient Hebrew • Used in Civil Communications • Mono-Alphabetic Substitution Technique 	<ul style="list-style-type: none"> • 300 BC • By Ancient Egypt • Used in Wars and in Civil Communications • Pictorial Writing Technique 	<ul style="list-style-type: none"> • 100 BC • By Julius Caesar and Roman Armies • Used in War • Mono-Alphabetic Shift Technique

2.2 Cryptography in the Middle Ages (Classic Cryptography)

According to Hashmi and Choubey (2018), around 500 – 600 BC, Cryptography became popular, so encryption followed these methods:

- Substitution
- Transposition
- Codes
- Additionally, Cryptanalysis began in the Medieval ("History of

Cryptography", 2023)

2.2.1 Substitution cryptographic method

This was the first cipher method which makes use of key model. Therefore, it can be called a ‘Substitution Cipher’. Key means replacing alphabet to other alphabet for some secret rule. This rule becomes called a key (Abbasi and Singh, 2021).

There are Two (2) applications of substitution method.

i. Mono-Alphabetic Cipher

According to Aung et al. (2019), in Mono-Alphabetic substitution, a character (or a symbol) in the plain text is always changed to the same character (or a symbol) in the cipher text regardless of its position in the text (Aung et al., 2019). Examples are: Additive cipher, Shift cipher, Caesar cipher, Multiplicative cipher, Affine cipher, etc.

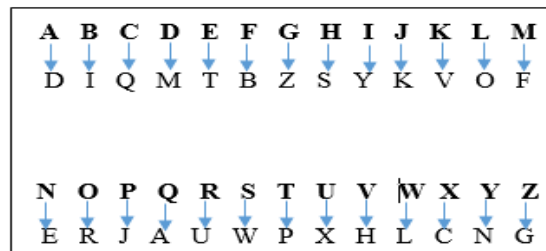


Figure 2: A Mono-Alphabetic Substitution Cipher (Hashmi and Choubey, 2018)

ii. Poly-Alphabetic Cipher

In Poly-Alphabetic substitution, each occurrence of a character may have a different substitute. (Aung et al., 2019). Examples of Poly-Alphabetic ciphers are: Vigenère cipher, Autokey cipher, Playfair cipher, Beaufort cipher, Running key cipher, Porta cipher, Hill cipher, One-Time pad, Rotor cipher, etc.

2.2.2 Transposition cryptographic method

According to Twum et al (2019), transposition ciphers shuffles characters around, instead of substituting them with other characters, as in the Substitution Method treated earlier. A transposition cipher is one which rearranges the order of the letters in the cipher text (encoded text), according to some predetermined method, without making any substitutions (Nrich, 2018).

E	N	E	M	Y	T	A
N	K	S	A	P	P	R
O	A	C	H	I	N	G
H	I	L	L	E	I	G
H	T	S	I	X	T	H
R	E	E	S	T	O	P

Plain Text: ENEMY TANKS APPROACHING HILL EIGHT SIX THREE STOP

Cipher Text: ENOHH RNKAI TEESC LSEMA HLISY PIEXT TPNIT OARGG HPXXX

Figure 3: A Simple Columnar Transposition Cipher (UMich, 2018).

2.2.3 Codebook cryptographic method

Codebook makes use of codes to replace a word or a phrase. Using Code, it was a good way to obfuscate meaning if the message is small and the codebooks are safe (Hashmi and Choubey, 2018).

plaintext	attack	to	taj	on	five	dec	eighteen
symbol	&	%	@	!	<	#	?

Figure 4: A Codebook Cipher Method (Hashmi and Choubey, 2018)

2.2.4 Cryptanalysis

Frequency Analysis technique was designed by Al-Kindi, an Arab mathematician, for breaking mono-alphabetic substitution ciphers. This was around AD 800, in the medieval ("History of Cryptography", 2023). Cryptanalysis means trying to break any security system (or cipher) by using unauthorized ways to access the information in that system. Thus, cryptanalysis works against cryptography. The cryptanalyst tries to find any weakness in the cryptographic system to get either the source of information (plaintext) or the key used in the encryption algorithm (Al-Janabi, Al-Khateeb and Abd, 2017). The objective of cryptanalyst is to be able to decrypt cipher text (Tiwari, Nandi and Mishra, 2013). In the modern era, among several instances, Brute-force key-space search has broken some real-world ciphers and applications, including single-DES, 40-bit "export-strength" cryptography, and the DVD Content Scrambling System. In 2008, researchers conducted a proof-of-concept break of SSL using weaknesses in the MD5 hash function and certificate

issuer practices that made it possible to exploit collision attacks on hash functions ("Cryptanalysis", 2023). In World War II, the Allies benefitted enormously from their joint success cryptanalysis of the German ciphers – including the Enigma machine and the Lorenz cipher – and Japanese ciphers, particularly 'Purple' and JN-25. In World War II, the Enigma cipher system was broken by Polish and British cryptographers. ("Cryptanalysis", 2023). Below is a summary of cryptographies used in the medieval period.

Period	Cryptographic Techniques			
Medieval (500 – 1500 CE)	(1). Substitution <ul style="list-style-type: none"> Makes use of Ciphers Substitutes alphabets with another Used in Civil Communications 	(2). Transposition <ul style="list-style-type: none"> Makes use of Ciphers shuffles characters around Used in Civil Communications 	(3). Codebook <ul style="list-style-type: none"> Makes use of Codes to replace words or phrases Used in Civil Communications where the message is small and codebooks are safe Used in Wars 	(4). Cryptanalysis <ul style="list-style-type: none"> The cryptanalyst tries to find any weakness in the cryptographic system in order to break the code. Thus, cryptanalysis works against cryptography.

2.3 Cryptography in the World War 1

According to Cthaeh (2021), Radio was invented at the very end of the 18th century and World War I and became the first big war in which it was used. Naturally, making communications more effective also increased communication traffic by several orders of magnitude. World War I has a timeline from 28th July, 1914 to 11th November, 1918 (Ray, 2018). According to Cthaeh (2021), World War I is the second largest military conflict in history, surpassed only by World War II. The war was fought between two camps — the Central Powers and the Allied Powers — and lasted until late 1918. The main participants on the side of the Central Powers were Germany, Austria-Hungary, the Ottoman Empire, and Bulgaria. On the side of the Allied Powers were France, Britain, Russia, and Italy. Many other countries joined the conflict at different stages (including the United States on the side of the Allied Powers). The invention of the electric telegraph increased the traffic of messages dramatically. Messages could now travel through electric wires close to the speed of light.

2.3.1 Standard codes used in World War I

Cthaeh (2021) stated that the most common use of codes was for naval, diplomatic, and strategic communication. In general, using codes is more cumbersome compared to ciphers, since the encoding/decoding process is significantly slower and the secure distribution of codebooks is always a challenging task, especially when the communicating parties are constantly on the move. On the other hand, these codes were considered far more secure than ciphers. That's why they were preferred for communication that required absolute secrecy.

Trench Codes: These were less sophisticated codes with a much smaller vocabulary of up to only a few thousand words, used by armies inside trenches. They were less secure but easier to distribute. The lower security wasn't necessarily a serious issue. Even if the enemy managed to break the code for a particular message, it wouldn't matter too much unless they break it fast enough. The situation on the battlefield is changing quickly and old information becomes useless very fast (Cthaeh, 2021).

2.3.2 Field ciphers used in World War I

i. Playfair (British): The Playfair cipher system was widely used by American army and English Army during the World War I (Shang & Lu, 2012). The British used it for tactical communication. Later on, the Americans picked it up too when they joined the war (Cthaeh, 2021).

ii. Interrupted Columnar Transposition (French): The French used the interrupted columnar transposition cipher for very similar purposes to the British's use of the Playfair cipher (tactical communication on the battlefield) (Cthaeh, 2021).

iii. Turning Grilles Cipher (German): This is a pure transposition cipher that uses a square made up of smaller squares. Crucially, there were holes at the positions of a quarter of the smaller squares. The Germans used squares of different sizes, depending on the length of the message they wanted to send (like 7×7 or 10×10), always removing a quarter of the small squares (Cthaeh, 2021).

iv. ADFGX and ADFGVX cipher (German): The cipher's name initially was **ADFGX** and shortly after it became **ADFGVX**, after a small modification. However, the ADFGVX modification doesn't change the nature of the cipher. Germany introduced it in early 1918 and used it for communications between divisions, corps, and army headquarters during the Spring Offensive I told you about earlier (Cthaeh, 2021).

v. Vigenere Cipher (Russia): Ernst Fetterlein was in the Tsarist Russian Ministry of Foreign Affairs from 1896 and solved (among others) German, Austrian and British codes. He became chief cryptographer with the rank of admiral. The Russians used an overcomplicated version of the Vigenère Cipher. It was broken within three days by Austro-Hungarian cryptanalyst Hermann Pokorny (Cthaeh, 2021).

2.3.3 Tele-printer ciphers used in World War I

In 1917, Gilbert Vernam proposed a tele-printer cipher in which a previously prepared key, kept on paper tape, is combined character by character with the plaintext message to produce the cypher text. This led to the development of electromechanical devices as cipher machines, and to the only unbreakable cipher, the One-Time pad (Rijmenants, 2022).

One-Time Pad

To perform one-time pad encryption, we need a key, called one-time pad. A one-time pad can be a single sheet, a booklet or a strip or roll of paper tape that contains series of truly random digits. A one-time pad set consists of two identical one-time pads, one pad called OUT and one called IN. To establish one-way communications, you only need one OUT pad for the sender and an identical copy called IN pad for the receiver. To communicate in both ways, you need two different one-time pad sets: person A has an OUT pad of which person B has the IN copy, and person B has another OUT pad of which person A has the IN copy (Rijmenants, 2022). Below is a summary of cryptography used in the World War 1

Periods	Cryptographic Techniques		
World War 1 (1914 - 1918)	(1). Codebooks <ul style="list-style-type: none"> Makes use of Codes to replace words or phrases Used in Civil Communications where the message is small and codebooks are safe Used in World War 1 (Codebook with super-encryption). Example: Trench Codes. 	(2). Field Ciphers <ol style="list-style-type: none"> i. PlayFair Cipher (British) ii. Interrupted Columnar Transposition (French) iii. Turning Grilles Cipher (Germany) iv. ADFGX and ADFGVX cipher (Germany) v. Vigenere Cipher (Russia) 	(3). Tele-Printer Ciphers <ul style="list-style-type: none"> This is a technique, in which a previously prepared key, kept on paper tape, is combined character by character with the plaintext message to produce the cypher text. Example: One Time Pad Cipher

2.4 Cryptography in the World War II

By World War II, mechanical and electromechanical cipher machines were in wide use (“History of cryptography”, 2023). The World War II has a timeline from 1939 to 1945. The principal belligerents were the Axis powers—Germany, Italy, and Japan—and the Allies—France, Great Britain, the United States, the Soviet Union, and, to a lesser extent, China (Hughes and Royde-Smith, 2023).

In the 1920s, various mechanical encryption devices were invented to automate the process of encryption. Most were based on the concept of a rotor, a mechanical wheel wired to perform a general substitution (Sokouti, Sokouti and Pashazadeh, 2009).

2.4.1 Cipher machines used in World War II

Enigma (Germany): As complicated as the Enigma was, it was broken during World War II. First, a team of Polish cryptographers broke the German Enigma and explained their attack to the British. The Germans modified their Enigma as the war progressed, and the British continued to cryptanalyze the new versions (Sokouti, Sokouti and Pashazadeh, 2009).



Fig 5: The German Enigma (“History of cryptography”, 2023)

Purple (Japan): In the early 1930s, the Japanese government purchased the commercial version of the Enigma machine from the German government in order to build an enhanced version of it. This cryptographic machine was named “Red” by the US government. Soon after the “Red” cipher was broken by the U.S.A, the Japanese government created a more evolved and secure cipher known as “97-shiki O-bun In-ji-ki” or “97 Alphabetical Typewriter”, named for its creation on the Japanese year 2597 in 1937. The US later named it as Purple. Unlike the Enigma machine, which used the blinking lights to represent the message, Purple used an electric typewriter, which could

write the message on paper. This was easy to use than the Enigma machine. However, it was heavy and tedious to carry in combat areas. It was a complex machine used to encrypt data not only in the 1930s, but even today. It falls under the category of homophonic substitution ciphers, where a single plaintext letter can be replaced by any of the different cipher text letters. (Shikhare, 2015).



Fig 6: The Japanese 'Purple' (Shikhare, 2015)

Typex (Britain): After the World War I, the British government in 1926, established the Inter-Departmental Cipher Committee to explore possible cipher machines to replace their current book cipher systems. In 1935, the Committee decided upon “Enigma type cipher machines improved through the use of ‘Type X’ attachments” or Typex. The Typex machine, developed by Wing Commander O.G.W. Lywood, was such a close relative of the Enigma machine that the British use Typex machines in place of Enigma when trying to decipher Enigma messages. When German soldiers recovered a Typex machine sans rotors, they successfully converted it into an Enigma machine. This similarity discouraged German cryptanalysts from attempting to cryptanalyze Typex enciphered messages because they believed Enigma to be unbreakable (Chang, 2012).



Fig 7: The British 'Typex' (Chang, 2012).

Sigaba (USA): SIGABA is a cipher machine used during World War II until the 1950s. It takes a shot at the electromechanical arrangement of rotors (Pal, Datta and Karmakar, 2020). In the 1930s, the U.S. Army cryptologist William Friedman and his assistant Frank Rowlett drew on this simple precept to conceive a cipher machine that was easy to use, simple to rekey, and ostensibly impossible to break. To the Army it was known as SIGABA, to the Navy, ECM (Electric Cipher Machine) II. Not only was SIGABA the most secure cipher machine of World War II, but it went on to provide yeoman service for decades thereafter (Mucklow, 2015)



Fig 8: The USA ‘SIGABA’ (Mucklow, 2015)

Below is a summary of cryptography used in the World War II.

Period	Cryptographic Techniques	
<p>World War II</p> <p>(In the 1920’s)</p>	<p>(1). Codebooks</p> <ul style="list-style-type: none"> Used in World War 2 (Eg. The Japanese JN-25 Code) 	<p>(1). Cipher Machines</p> <p>Mechanical encryption devices that were invented to automate the process of encryption. Most were based on the concept of a rotor, a mechanical wheel wired to perform a general substitution.</p> <p>Examples:</p> <ol style="list-style-type: none"> Enigma (Germany) Purple (Japan) Typex (Britain) Sigaba (USA)

requires two separate keys, one of which is private and one of which is public. The public key encrypts the message while the private key decrypts the encrypted message. Public Key Cryptography is a very advanced form of cryptography. Officially, Whitfield Diffie and Martin Hellman invented it in 1975. The British Clifford Cocks of Communications-Electronics Security Group (CESG) of (Government Communications Headquarters - GCHQ) first discovered the basic technique of public key cryptography in 1973 but this was a secret until 1997. The figure below depicts a public key cryptography.

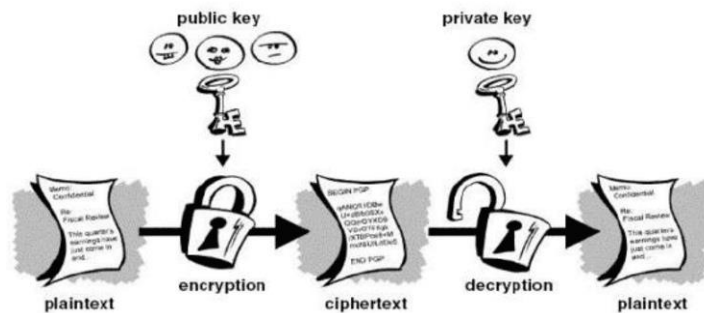


Figure 10: Public (Asymmetric) Key Cryptography (Adomey, 2020)

Some examples of asymmetric cryptography are: Rivest-Shamir-Adleman (RSA) Algorithm, Digital Signature Standard, ElGamal, etc.

2.5.3 Hash functions

According to Kundu and Dutta (2020), hash functions refer to a function that compresses a string of arbitrary input to a string of fixed length. In other words, we get a fixed-length message digest out of a variable-length message. Compared to the message the digest is normally much smaller. The main purpose of hashing is related with message security like protecting message integrity, authenticity, etc. Wahome (2021) further explained that using hash functions for cryptography refers to cryptographic hash function. He continued that all cryptographic hash functions are hash functions, but not all hash functions are cryptographic hash functions. Mathematically, Wahome classified cryptographic hash functions into two classes:

- Unkeyed hash functions also known Manipulation Detection Code (MDC) or Message Authentication Code (MAC) with a single parameter, an input message.
- Keyed hash functions with two distinct input, an input message and a secret key.

Wahome (2021) also listed the examples of cryptographic hash functions

as follows:

- The Secured Hash Algorithm (SHA) family - They are six hash functions: SHA -0, SHA – 1, SHA – 224, SHA – 256, SHA – 384 and SHA – 512. The first four operate on 512-bit message blocks divided into 32-bit words and the last two on 1024-bit blocks divided into 64-bit words. Bitcoin, the original and largest cryptocurrency (at the time of writing), uses the SHA-256 hash function.
- **The MD (Message Digest)** family — comprises of MD2, MD4, MD5 and MD6 authored by Ronald Rivest for RSA security and was adopted as the Internet Standard RFC 1321.
- **RIPEMD (RACE Integrity Primitives Evaluation Message Digest)** — a family of cryptographic hash functions based upon the design principles used in MD4 developed by Hans Dobbertin, Antoon Bosselaers, and Bart Preneel at the COSIC research group at the Katholieke Universiteit Leuven. RIPEMD-160 produces a hash digest of 160 bits (20 bytes).
- **Whirlpool** — designed by Vincent Rijmen and Paulo S. L. M. Barreto, this hash function based on a substantially modified version of the Advanced Encryption Standard (AES). Whirlpool produces a hash digest of 512 bits (64 bytes).
- **BLAKE** — a hash function submitted to the NIST hash function competition by Jean-Philippe Aumasson, Luca Henzen, Willi Meier, and Raphael C.-W. Phan. It is based on Dan Bernstein’s ChaCha stream cipher, but a permuted copy of the input block, XORed with round constants, is added before each ChaCha round.
- **Curl-P** — a hash function formerly used in IOTA Signature Scheme (ISS). IOTA is a cryptocurrency designed for use with the Internet of Things (IoT) and automotive ecosystems. ISS is based on Winternitz One-Time Signatures but unlike traditional Winternitz, in IOTA users sign the hash of a message. Thus, the security of ISS relies on its cryptographic hash function, which was Curl-P-27.

2.5.4 Hybrid cryptographic systems

Hybrid cryptography means combining two or more cryptosystems. There are benefits and limitations in both symmetric and asymmetric

ciphers. Symmetric ciphers are fast but suffer key exchanging. Asymmetric ciphers solve the key exchange problem, in other words secure, but slow. Practically, hybrid cryptography, which is an integration of symmetric and asymmetric ciphers, makes use of the efficiency of symmetric ciphers and the simplicity and security of asymmetric ciphers (Murad and Rahouma, 2021b).

2.5.4.1 Approaches to hybrid cryptography

In this study, three (3) approaches to hybrid cryptography were studied:

Double Encryption (of Symmetric or Asymmetric)

The first approach, according Murad and Rahouma (2021a), involves performing two layers of symmetric or asymmetric encryption. Here, data is double encrypted by applying two consecutive, either symmetric or asymmetric ciphers in a row. See figure below.

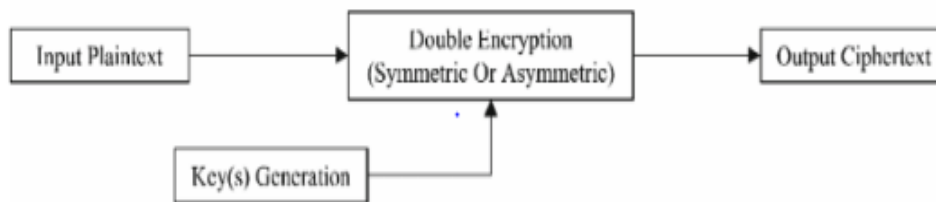


Figure 11: Hybrid scheme uses double encryption of either symmetric ciphers or asymmetric ciphers for data encryption (Murad and Rahouma, 2021a)

Symmetric / Asymmetric Hybrid Cryptography

As shown in the next figure below, this approach utilizes a symmetric algorithm to encrypt the data and applies an asymmetric algorithm to encrypt the secret key. See figure below.

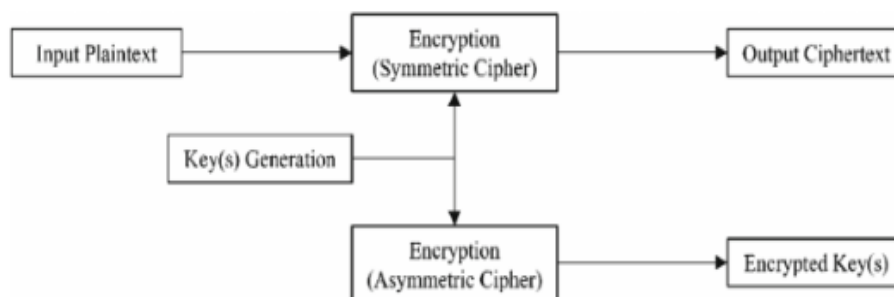


Figure 12: Hybrid scheme uses symmetric ciphers for data encryption and asymmetric ciphers for key encryption (Murad and Rahouma, 2021a)

Cryptography with other Supportive Methods (i.e. with other technologies)

To further strengthen cryptography, researchers have presented schemes where supportive methods were used to improve cryptography security level. Examples of such supportive methods are:

- Hybrid cryptography and steganography method to embed encrypted text message within image (Jassim, et al., 2019)
- A hybrid scheme of cryptography and watermarking (Kaur and Kaur, 2016)
- A hybrid cryptographic technique using RSA algorithm and scheduling concepts (Shankar and Akshaya, 2014)

These supportive methods are applied to increase the strength of a symmetric / asymmetric hybrid algorithm.

Below is a summary of cryptography used in the modern era.

Period	Cryptographic Techniques			
Modern Era	<p>(1). Symmetric (Secret key) Cryptography</p> <p>Sender and receiver of a message share a single, common key, used to encrypt and decrypt the message.</p> <p>Examples:</p> <p>i). Data Encryption Standard (DES)</p> <p>ii). Triple-DES</p> <p>iii). Advanced Encryption System (AES)</p> <p>iv). Rivest Cipher 4 (RC4)</p> <p>Etc.</p>	<p>(2). Asymmetric (Public key) Cryptography</p> <p>This requires two separate keys, one of which is private and one of which is public. The public key encrypts the message while the private key decrypts the encrypted message.</p> <p>Examples:</p> <p>i). Rivest-Shamir-Adleman Algorithm (RSA)</p> <p>ii). Digital Signature Standard</p> <p>iii). ElGamal</p> <p>Etc.</p>	<p>(3). Hash Functions</p> <p>Here, we get a fixed-length message digest out of a variable-length message.</p> <p>Examples:</p> <p>i). Secured Hash Algorithm (SHA) family</p> <p>ii). MD (Message Digest) family</p> <p>iii). RIPEMD family</p> <p>iv). Whirlpool</p> <p>v). Blake</p> <p>vi). Curl-P</p>	<p>(4). Hybrid Cryptography</p> <p>Hybrid cryptography means combining two or more cryptosystems.</p> <p>Approaches:</p> <p>1). Double Encryption (AES + AES)</p> <p>2). Symmetric + Asymmetric (AES + RSA)</p> <p>3). Cryptography + Supportive Methods. Eg:</p> <p>- (RSA + Scheduling Concepts)</p>

3.0 Conclusion

Based on the above reviews, cryptography has evolved in so many ways and is still evolving. It has been found to be applied in the following ways:

i. Civil Communication

Cryptography is applied in encrypting messages in civil communications or messages between two regular individuals or organizations. Starting from antiquity, through the medieval, and through the world wars, and in the modern era, messages can be encrypted to ensure confidentiality. Emails are usually encrypted in order to keep them confidential. As messages travel through communication links, both wired and wireless, they are often encrypted.

ii. Cryptanalysis

Cryptanalysis is as an application of cryptography, though as a reverse process. Cryptanalysis began in the Medieval period. This is because classical cryptography began in this era, with the introduction of key-based cryptography or ciphers. The medieval period cryptographic methods and those used in the world wars were at a point in time broken. In this modern era, cryptographic systems are not easily broken, because, they cannot be solved by hand. However, the One-Time-Pad is a Tele-Printer Cipher which has never been broken.

iii. Wars

In antiquity, Hieroglyphs were used to encrypt messages between soldiers. Cryptography in wars was mostly applied in the World War I and in the World War II. Cryptography is very essential during wars since each army group needs to frequently send messages to their colleagues in case of a need of unfavorable circumstances like need for back-up, need for a retreat, need for change of plans or change of direction, need for supply of more ammunitions. The message must be confidential, otherwise the enemy camp will know their plans and move ahead of them.

iv. E-Commerce

Cryptography is very important and is carefully applied for commercial purposes. Encryption keeps your data secure when you're shopping or banking online. It scrambles data like your credit card details and home address to ensure hackers can't misuse this information. Cryptography in e-commerce ensures data privacy.

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Use of Fenton's Reagent for Pollutants Removal in Pharmaceutical Effluent

E.I. Madukasi and O.B.Tojuola

Abstract

Effluent from a pharmaceutical factory producing a single chemical product was treated on a bench scale with advance oxidation process (H_2O_2 & Fe^{2+}). The effluent was as a result of the factory treatment of the pharmaceutical wastewater by UASB (up flow anaerobic sludge bed) and a SBR (sequencing batch reactor) process. The chromatechemical oxygen demand (CODcr) range of the discharged effluent was between 8000-10,000mg/L with some residual recalcitrant compounds. The residual recalcitrant compounds which were measured by gas chromatography mass spectrometry (GC-MS) mainly consisted of alcohols, phenols and nitrogenous and sulfur compounds. The experimental variables studied include dosages of Fe^{2+} , H_2O_2 and mixing speed. The result showed that the oxidation by Fenton's reagent was best when concentration of iron (II) sulfate and hydrogen peroxide were $[\text{Fe}^{2+}] = 1.093\text{mmol/L}$; $[\text{H}_2\text{O}_2] = 2.5\text{mmol/L}$ at pH = 3.0 for 30min at 80rpm; followed by conditioning with lime (1%) to pH = 8.0 where coagulation by iron hydroxide took place over 20min. Under these optimal operating conditions, the maximum removal efficiency for CODcr, Color and the aromatic compounds were 56%, 95% and 90% respectively.

Keywords: Fenton reagent; pharmaceutical effluent; hydrogen peroxide; ferrous salt; effluent treatment; chemical treatment

Introduction

The process of toxicity reduction in pharmaceutical wastewater is of paramount importance due to known fact that substances synthesized in pharmaceutical industry are either toxic inhibitory compound or structurally complex organic chemicals that are resistant to biological degradation and consequent accumulation in the environment as well as possible carcinogenic and mutagenic effect (Jia *et al*, 2015; Ronak & Shweta, 2015; Balcioglu & Otker, 2003). This makes conventional treatment methods inadequate for the treatment of pharmaceutical wastewater. One of the possible methods for their degradation and removal is chemical oxidation, especially advanced oxidation

processes (AOPs) using for example O_3/H_2O_2 (peroxone); $O_3/H_2O_2/UV$; O_3/UV ; H_2O_2/UV ; TiO_2/UV and Fenton reactions. These processes involve the in-situ formation of highly reactive hydroxyl radicals ($\bullet OH$), which react quickly and non-selectively with almost all organic pollutants (Vrushali & Gawande, 2015; Tijani *et al.*, 2016; Sanchis *et al.*, 2013). One of the most important advance oxidation processes used to generate hydroxyl radicals employs the Fe^{2+}/H_2O_2 system where the catalyst (ferrous ions) is dissolved in water, thus being known as Fenton process (Yuan *et al.*, 2013). Fenton's reaction is one of the most effective methods of oxidation of organic pollutants that are oxidatively degraded by hydroxyl radicals generated from H_2O_2 in the presence of Fe^{3+} as a catalyst (Hartmann *et al.*, 2010; Maezono *et al.*, 2011). $Fe^{2+} + H_2O_2 \longrightarrow Fe^{3+} + OH + OH\bullet$ equation1.

When ferrous salts are used, the hydroxyl radical is produced immediately by the rapid reaction between ferrous ion and H_2O_2 (equation1). Fe^{3+} can also be used to decompose H_2O_2 and to produce oxidative radicals in the Fenton-like process. With Ferric salts, the hydroxyl radical is produced in a two-stage process with the slow reaction between ferric ion and H_2O_2 (equation2) followed by the rapid reaction between the produced ferrous ion and additional hydrogen peroxide [Kiwi *et al.*,1993]. $Fe^{3+} + H_2O_2 \longrightarrow Fe^{2+} + HO_2\bullet + H^+$ equation 2.

In most applications, it does not matter whether Fe^{2+} or Fe^{3+} ions are used to catalyze the reaction, although some authors (Pera-Titus *et al.*, 2004; Walling & Amarnath, 1982) suggested that if low doses of Fenton's reagent are used ferrous ions may be preferable. The efficiency of Fenton's process depends on H_2O_2 and Fe^{2+} concentrations and the pH of the reaction. According to some previous researcher's report, pH value should range from 3 to 5 (Mohammadine *et al.*, 2014; Navalon *et al.*, 2010 and Maezono *et al.*, 2011).

Fenton reagent was found to be very effective in treating various industrial wastewater components, including aromatic & aliphatic compounds (Barbusinski & Filipek, 2001), a wide variety of dyes (Hsueh *et al.*, 2005) as well as many other substances, including pesticides (Barbusiñki & Filpek., 2001). In this work, we present the oxidative treatment of pharmaceutical effluent that contained some recalcitrant compounds by Fenton reaction, using COD as determinand for the parameter only. This is because the pharmaceutical effluent will be subjected to critical biological treatment but effort was geared towards understanding the behavior of the effluent in a chemical treatment method hence the use of a single and most suitable parameter for efficiency determination.

Material & Methods

Wastewater:

The pharmaceutical effluent is from a medium scale drug manufacturing plant situated in Ota near Lagos State Nigeria. The presence of toxic compounds in wastewater was both due to the factory product as well as chemicals used in sterilizing the manufacturing equipment. The intermittent cleaning and disinfecting of the tanks used in the production as well as domestic utilization of the tap water make up the wastewater coming out of the plant. The plant manufacturing line is operated as batch reactor. All the characteristics of the wastewater (Table1) were measured according to procedures described in standard methods (AWWA, 1995)

Table1: **Pharmaceutical Effluent Chemical Characterization**

PARAMETERS	MEAN VALUE
pH	4,3 ± 0,3
BOD5 (mg L-1)	1370 ± 260
COD (mg L-1)	8030 ± 800
Suspended solids (mg L-1)	65 ± 10
Total solids (mg L-1)	1400 ± 400
Fats and Oils (mg L-1)	45 ± 25
Detergents (mg L-1)	100 ± 50
Odour	Noticeable, peculiar, savoury

Experimental procedure:

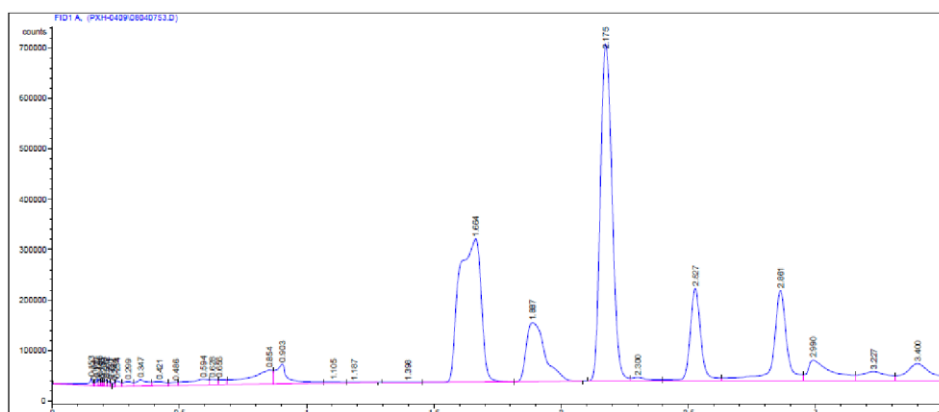
The following parameters of Fenton's reaction were examined and optimized; hydrogen peroxide and ferrous concentration, $[Fe^{2+}]$: $[H_2O_2]$ ratio, and initial pH of the reaction. A liter of wastewater was added into one liter Erlenmeyer flask which served as the reactor, acidified with H_2SO_4 (Fenton reaction is effective at acidic pH range). Since the initial pH of the wastewater is above 5.0, the sample was acidified to the desired value in the pH range of 2.5 –4.0. After which various doses of 30% H_2O_2 and solid $FeSO_4 \cdot 7H_2O$ were added, the mixture was vigorously stirred for 1hour at 80rpm (oxidation process), then pH was adjusted to 8.0 with 1% lime and coagulated at 30rpm for 20min. it was allowed to sediment and chemical oxygen demand (COD) and residual H_2O_2 were determined in the clear solution. COD tests were made after total removal of residual H_2O_2 . The residual H_2O_2 can increase the COD value since it acts as a reductant, especially in the chromate based analysis of COD determination. Talinli and Anderson (1992) investigated the reducing effect of H_2O_2 on $K_2Cr_2O_7$ and they showed linear relationship between concentration of H_2O_2 and COD.

Residual H₂O₂ removal

This was achieved by raising the pH of the solution (pH=10.5) at high temperature (45) in the presence of Fe³⁺ with stirring at 65rpm and was sit overnight (Walling & Amarnath, 1982; Krzysztof Barbusinski, 2009).

Analytical methods

Aromatic and aliphatic compounds were analyzed by Infrared spectrometer (FTIR spectrometer) and confirmed with gas chromatography – mass spectrometry (GC– MS) as shown in fig1. The trace element analyses were carried out with inductive coupled plasma (optimal emission spectrometer, optima 5300DV). COD (closed reflux, trimetric method). Concentration of residual H₂O₂ was analyzed by the KMnO₄ method.



concentrations. The result showed that the efficiency of Fenton reaction depends on the concentration of Fe^{2+} as occurs in the classical Fenton reagent process. (Rajesh & Raman, 2013) have demonstrated that the COD removal is nearly the same using either Fe^{2+} or Fe^{3+} in the degradation of a textile wastewater by the Fenton process. The maximum COD removal achieved in this study was between 40 – 56% depending on the hydrogen peroxide dosage.

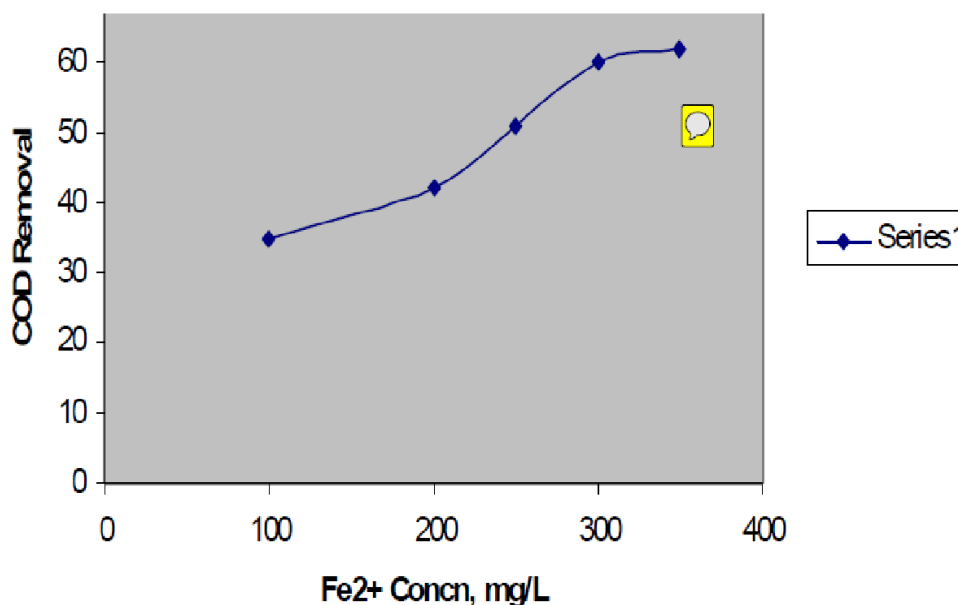


FIG. 2:: **Effect of Fe^{2+} Concentration variation**
 H_2O_2 @ 1.6M; pH = 2.5; Mixing speed = 100rpm @ 30min

Effect of temperature and pH

An initial experiment was carried out at room temperature and at 50°C, to show the effect of temperature on COD removal efficiency but no significant differences were observed in the treatment efficiency for the tested temperatures (data not shown). Thus all further work was carried out at room temperature. Research findings indicate that the temperature of the wastewater almost does not affect the efficiency of COD removal in Fenton's oxidation (Peral *et al.*, 2002; Casero *et al.*, 1997), although the redox reaction can be accelerated by rising the temperature as expected. The time required for the oxidation to be completed at room temperature was about 15–20 times longer than at 50°C which required several minutes (data not shown). When tested with initial pH range of 2.5 – 4.5, no significant differences in the treatment efficiency were observed although pH 3.5 showed slightly better results. This finding is in adherence with the recent research reports that suggest that the optimum pH for Fenton oxidation is between 3–5 and that it is independent of the nature of the wastewater. (Tambosi *et al.*, 2006; Hsueh *et al.*, 2005) all observed that pH affects significantly the degradation of organics by Fenton reaction and acidic condition is required to produce sufficient hydroxyl radicals

by the decomposition of hydrogen peroxide catalyzed by ferrous ions. In a recent study, (Zhang *et al.*, 2005) reported the optimum pH as 2.5 for the treatment of landfill leachate by Fenton's oxidation.

Effect of H₂O₂ concentration

The degradation rate of organics in wastewater increases as the concentration of H₂O₂ increases until a critical H₂O₂ concentration is achieved (Huseh, *et al.*, 2005). Above this critical concentration, the degradation rate of organic compounds decreases as a result of the scavenging effect, according to equation 3 $H_2O_2 + OH\cdot \rightarrow HO_2\cdot + H_2O$ (3) Fig.3 clearly shows that as the concentration of H₂O₂ increases, there was an increase in the COD removal efficiency up to the optimum concentration of 15ml/L. Above this amount of H₂O₂, there was decrease in the efficiency removal.

Conclusion

The Fenton process could be applied to pharmaceutical effluent. The COD removal efficiency using oxidation was greatly affected by the initial pH of the solution. The most efficient reaction was observed at a pH of 3.0 and the optimum coagulation pH range to maximize the COD removal efficiency was between 6.0 – 8.0. For a pharmaceutical wastewater with a COD range of 8000 – 10000mg/L, average COD removal efficiency was highest when the ratio of H₂O₂/Fe²⁺ was about 150–250. At 0.3M H₂O₂ and 0.012M the optimum COD removal efficiency of 65% was achieved. Fenton reagent could be used to treat pharmaceutical wastewater that contains some constituents that are extremely toxic to biological processes hence viewed as biocides. Fenton's reaction proves to be an efficient treatment technology when biological treatment is not feasible.

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Uniqueness of Optimal Control for the Relative Controllability of Neutral Integro-differential Systems in Banach Spaces with Distributed Delays in the Control

Paul Anaetodike Oraekie

ABSTRACT

A new method of approach is derived for the proof of the existence of an optimal control for Neutral Integrodifferential Systems in Banach Spaces with Distributed Delays in the Control, using the properties of optimal control energy function. The set functions upon which our studies hinged were extracted from the mild solution of the system. Use was also made of the unsymmetric Fubini theorem to establish the mild solution. Necessary and sufficient conditions for an admissible control to be an optimal control are established.

Keywords: Optimal control, uniqueness, controllability, controllability grammian, set functions.

INTRODUCTION:

The pioneering work of Vito Volterra on the integration of the differential equations of dynamics and partial differential dynamical systems published in 1884 gave vent to the conception of integral equations of the volterra type (**Oconnor and et al (2005);Oraekie(2014)**). It is equally observed in **Balachandran and Dauer (1989); Oraekie (2017)** that the mixed initial boundary hyperbolic partial differential equation which arises in the study of Lossless transmission lines can be replaced by an associated neutral differential equation. This equivalence has been the basis of a number of investigations of the stability properties of distributed networks. (see **Balachandran and Dauer (1997) and Oraekie(2015)**).

The problem of controllability of linear and nonlinear systems represented by ordinary differential equation in finite dimensional space has been extensively studied. Many authors have extended the controllability concept to infinite dimensional systems in Banach spaces with bounded operators (see **Naito (1989)**). Naito has studied the controllability of semi linear systems. **Yamamoto and Park (1990)** discussed the same problem for parabolic equation with uniformly bounded nonlinear term. While **Chukwu and Lenhart (1991)** studied the controllability of nonlinear systems in abstract spaces. **Quinn and Carmichael (1984)** showed that

the controllability problem in Banach space can be converted into a fixed point theorem problem for a single-valued mapping. **Balachandran (1996, 1998); Oraekie(2017)** had studied the controllability and local null controllability of Sobolve type integrodifferential systems and functional differential systems in Banach spaces by using Schauders fixed point theorem.

The purpose of this paper is to investigate the uniqueness of the optimal controllability of the abstract neutral functional integrodifferential systems with distributed delays in the control of the form.

$$\frac{d}{dt}[x(t) - g(t, x_t)] + A(t)x(t) = \int_0^t f(s, x_s)ds + \int_{-h}^0 (d_s D(s, r)u(s+r)) \quad (1.1)$$

$$x(t_0) = x_0 = \phi \in B, \quad t \in [0, a] = T$$

where B is the phase space, the state variable $x(\cdot)$ takes values in Banach space X and the control function $u(\cdot)$ is given in $L_2(J, U)$ (where $|u_j| \leq 1, \quad j = 1, 2, \dots$), the Banach space of admissible control functions with u a Banach space. D is a bounded linear operator from U into X , the unbounded linear operators $-A$ generates an analytic semi group and $f, g \in J \times B \rightarrow X$ are appropriate functions.

2.0 Preliminaries and Definitions

Throughout this work X will be a Banach space with norm $\|\cdot\|, -A: D(A) \rightarrow X$ will be the infinitesimal generator of a compact analytic semigroup of uniformly bounded linear operator $T(t)$. Let $0 \in \rho(A)$, then it is possible to define the fractional power A^α , for $0 < \alpha \leq 1$, as a closed linear operator on its domain $D(A^\alpha)$.

To study the system (1.1), we assume that the histories

$$x_t: (-\infty, 0) \rightarrow X, \quad x_t(\theta) = x(t + \theta)$$

belong to some abstract phase space B , which is defined axiomatically.

Thus, B will be a linear space of functions mapping $(-\infty, 0]$ into X , endowed with a norm $\|\cdot\|_B$.

Let us assume that B satisfies the following axioms:

(1). If $x: [\alpha, \alpha + a] \rightarrow X, \quad a > 0$, is continuous on $[\alpha, \alpha + a]$ and $x_\alpha \in B, \quad$ then for every time $\tau \in [\alpha, \alpha + a]$ the following conditions hold:

- (a) x_t is in B ;
- (b) $\|x(t)\| \leq k \|x_\tau\|_B$;

$$(c) \|x_\tau\|_B \leq H(\tau - \alpha) \sup\{\|x(s)\| : \alpha \leq s \leq \tau\} + M(\tau - \alpha) \|x_\alpha\|_B.$$

Here, $k > 0$ is a constant, $H, M: [0, \infty) \rightarrow [0, \infty)$.

H is continuous and M is locally bounded, and K, H, M are independent of $x(\tau)$.

(d) For the function $x(\cdot)$ in (1), x_t is a B -valued continuous function on $[\alpha, \alpha + a]$;

(2) The space B is a complete space.

Now we can give basic assumptions on the system (1.1).

(i) $g: [0, a] \times B \rightarrow X$ is a continuous function, and there exists a constant $\lambda \in (0, 1)$ and $P, P_1 > 0$, such that the function g is X_λ -valued and satisfies the Lipschitz condition:

$$\|A^\lambda g(t_1, \phi_1) - A^\lambda g(t_2, \phi_2)\| \leq P(|t_1 - t_2| + \|\phi_1 - \phi_2\|_B)$$

For $0 \leq t_1, t_2 \leq a$; $\phi_1, \phi_2 \in B$, and the inequality

$$\|A^\lambda g(t, \phi)\| \leq P_1(\|\phi\|_B + 1) \text{ holds for } t \in J = [0, a], \phi \in B.$$

(3) The function $f: [0, a] \times B \rightarrow X$ satisfies the following conditions:

(i) For each $t \in J$, the function $f(t, \cdot): B \rightarrow X$ is continuous and for each $\phi \in B$, the function $f(\cdot, \phi): J \rightarrow X$ is strongly measurable,

(ii) For each positive number n , there is a positive function $\alpha_n \in L_1([0, a])$ such that

$$\sup \|f(t, \phi)\| \leq \alpha_n(t)$$

$$\|\phi\|_B \leq n$$

and

$$\liminf_{n \rightarrow \infty} \frac{1}{n} \int_0^a \int_0^t \alpha_n(s) ds dt = \gamma < \infty$$

(4) The linear operator W from U into X is defined by

$$Wu = \int_0^a T(t-s) \left[\int_{-h}^0 d_s C(s, l) \right] u(s+l) ds$$

and there exists a bounded invertible operator w^{-1} defined in $L_2(J; U) / \ker w$, where C is a bounded linear operator.

2.01: Variation of parameters

The function $x(\cdot): (-\infty, a] \rightarrow X$ is a solution of system (1.1) if $x_0 = \phi$,

then the restriction of $x(\cdot)$ to the interval $[0, a]$ is continuous and for each

$0 \leq t \leq a$, the function $AT(t-s)g(s, x_s)$, $s \in [0, t]$ is integrable and

the following integral equation is the required solution of system (1.1).

$$x(t) = T(t)[\phi(0) - g(0, \phi)] + g(t, xt) - \int_0^t AT(t-s)g(s, x_s)ds + \int_0^t T(t-s) \left[\int_{-h}^0 (d_S C(s, l)u(s+l) + \int_0^s f(\tau, x_\tau)d\tau) \right] ds, t \in J \dots \dots \dots (2.1)$$

$$(2.1) \Rightarrow x(t) = T(t)[\phi(0) - g(0, \phi)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s) ds + \int_0^t T(t-s) \left[\int_{-h}^0 (d_S C(s, l)u(s+l) \right] ds + \int_0^t T(t-s) \left[\int_0^s f(\tau, x_\tau)d\tau \right] ds \dots (2.2)$$

The fourth term in the right – hand side of system (2.2) contains the values of the control $u(t)$ for $t < 0$, as well as for $t < 0$.

The values of the control $u(t)$ for $t \in [0 - h, 0]$ enter into the definition of the initial complete state z_{t_0} .

To separate them, the fourth term of system (2.2) must be transformed by changing the order of integration. Using the unsymmetric Fubini theorem, we have the following equalities:

$$x(t) = T(t)[\phi(0) - g(0, \phi)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s)ds + \int_{-h}^0 d_S C \left(\int_0^t T(t-s)C(s, l)u(s+l)ds \right) + \int_0^t T(t-s) \left[\int_0^s f(\tau, x_\tau)d\tau \right] ds \dots \dots \dots (2.3)$$

$$= T(t)[\phi(0) - g(0, \phi)] + g(t, xt) - \int_0^t AT(t-s)g(s, x_s)ds + \int_0^t T(t-s) \left[\int_0^s f(\tau, x_\tau)d\tau \right] ds + \int_{-h}^0 d_S C \left(\int_{0+l}^{t+l} T(t-s)C(s-l, l)u(s-l+l)ds \right)$$

$$= T(t)[\phi(0) - g(0, \phi)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s)ds + \int_0^t T(t-s) \int_0^s f(\tau, x_\tau)d\tau ds + \int_{-h}^0 d_S C \left(\int_{0+l}^0 T(t-s)C(s-l, l)u_0(s)ds \right)$$

$$+ \int_{-h}^0 d_S C \left(\int_0^{t+l} T(t-s) C(s-l, l) u(s) ds \right) \dots\dots\dots (2.4)$$

where d_S denotes that the integration is in the Lebesgue – Stieltjes sense with respect to the variable s in the function $C(s, l)$.

Let us introduce the following notation:

$$\hat{C}(s, l) = \begin{cases} C(s, l) & \text{for } s < t, l \in R \\ 0 & \text{for } s > t, l \in R \end{cases} \dots\dots\dots (2.5)$$

Hence $x(t)$ can be expressed in the following form:

$$\begin{aligned} x(t) = & T(t)[\varnothing(0) - g(0, \varnothing)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s) ds \\ & + \int_0^t T(t-s) \int_0^s f(\tau, x_\tau) d\tau ds + \int_{-h}^0 d_S C \left(\int_{0+l}^0 T(t-s)C(s-l, l)u_0(s)ds \right) \\ & + \int_{-h}^0 d_S C \left(\int_0^t T(t-s)\hat{C}(s-l, l)u(s)ds \right) \dots\dots\dots (2.6) \end{aligned}$$

Using again the unsymmetric Fubini theorem, the equality (2.6) can be rewritten in more convenient form as follows:

$$\begin{aligned} x(t) = & T(t)[\varnothing(0) - g(0, \varnothing)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s) ds \\ & + \int_0^t T(t-s) \int_0^s f(\tau, x_\tau) d\tau ds + \int_{-h}^0 d_S C \left(\int_l^0 T(t-s)Cs-l, l)u_0(s)ds \right) \\ & + \int_0^t \left(\int_{-h}^0 T(t-s)d_S\hat{C}(s-l, l)u(s)ds \right) \dots\dots\dots (2.7) \end{aligned}$$

Now let us consider the solution $x(t)$ of system (1.1) for $t = t_1 = a$.

$$x(t) = T(t)[\varnothing(0) - g(0, \varnothing)] + g(t_1, x_{t_1}) - \int_0^{t_1} AT(t_1-s)g(s, x_s) ds$$

$$\begin{aligned}
 & + \int_0^t T(t-s) \int_0^s f(\tau, x_\tau) d\tau ds + \int_{-h}^0 d_s C \left(\int_{0+l}^0 T(t-s) C(s-l, l) u_0(s) ds \right) \\
 & + \int_0^{t_1} \left(\int_{-h}^0 T(t_1-s) d_s \hat{C}(s-l, l) u(s) ds \right) \quad (2.8)
 \end{aligned}$$

Consider system (2.7), for brevity, let,

$$\beta(t) = T(t)[\phi(0) - g(0, \phi)] + g(t, x_t) - \int_0^t AT(t-s)g(s, x_s) ds \quad \dots \dots \dots \quad (2.9)$$

$$\mu(t) = \int_0^t T(t-s) \int_0^s f(\tau, x_\tau) d\tau ds + \int_{-h}^0 d_s C \left(\int_{0+l}^0 T(t-s) C(s-l, l) u_0(s) ds \right) \quad (2.10)$$

$$z(t, s) = \int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \quad \dots \dots \dots \quad \dots \dots \dots \quad \dots \dots \dots \quad (2.11)$$

Substituting (2.9), (2.10), (2.11) in (2.7), we have a precise variation of constant formula for system (1.1) as

$$x(t, x_0, u) = \beta(t) + \mu(t) + \int_0^t z(t, s)u(s)ds \quad \dots \quad \dots \quad (2.12)$$

Definition 2.1 (Complete State)

The complete state for system (1.1) is given by the set $g(t) = \{x, u_t\}$.

Definition 2.2 (Relative Controllability)

The system (1.1) is said to be relatively controllable on $[0, a]$ if for every initial complete state $g(0)$ and $x_1 \in X$, there exists a control function $u(t)$ defined on $[0, a]$ such that the solution of system (1.1) satisfies $x(t_1) = x_1$.

2.02: Basic Set Functions and Properties.

Definition 2.3 (Reachable set)

The reachable set for the system (1.1) is given as

$$R(t_0, 0) = \left\{ \int_0^{t_1} \left[\int_{-h}^0 T(t_1-s) d_s \hat{C}(s-l, l) \right] u(s) ds \right\}$$

Where $U = \{u \in L_2([0, a]; X) : |u_j| \leq .1 ; j = 1, 2, \dots, m\}$

Definition 2.4 (Attainable set)

The attainable set for the system (1.1) is given as :

$$A(t, 0) = \{x(t, x_0, u) : u \in U\}, \text{ Where } U = \{u \in L_2([0, a]; X) : |u_j| \leq .1; j = 1, 2, \dots, m\}$$

Definition 2.5 (Target set)

The target set for system (1.1) denoted by $G(t_1, 0)$ is given as:

$$G(t_1, 0) = \{x(t, x_0, u) : t_1 \geq \tau > 0 \text{ for fixed } \tau \text{ and } u \in U\}$$

Definition 2.6 (Controllability grammian)

The controllability grammian of the system (1.1) is given as:

$$W(t_1, 0) = \int_0^{t_1} \left[\int_{-h}^0 T(t_1 - s) d_S \hat{C}(s - l, l) \right] \left[\int_{-h}^0 T(t_1 - s) d_S \hat{C}(s - l, l) \right]^T$$

Where T denotes matrix transpose.

2.03: Relationship Between the Set Functions

We shall first establish the relationship between the attainable set and the reachable set to enable us see that once a property has been proved for one set, then it is applicable to the other.

From equation (2.7),

$$A(t, 0) = \eta(t) + R(t, 0), \text{ for } u \in U, t \in [0, a],$$

$$\text{Where } \eta(t) = \beta(t) + \mu(t).$$

This means that the attainable set is the translation of the reachable set through $\eta \in X$.

Using the attainable set, therefore, it is easy to show that the set functions possess the properties of convexity, closeness and compactness.

Also, the set functions are continuous on $[0, \infty]$ to the metric space of compact subject of $X = E^n$. **Chukwu (1988) and Gyori (1982)** give impetus for adaptation of the proofs of these properties for system (1.1).

Definition 2.7 (Properness)

The system (1.1) is proper in $X = E^n$ on $[0, a]$ if $\text{span } R(t, 0) = X = E^n$ i. e if

$$C^T \left[\int_{-h}^0 T(t - s) d_S \hat{C}(s - l, l) \right] = 0 \quad \text{a. e.}$$

$$a > 0 \Rightarrow C = 0; C \in X = E^n$$

3. Main Results

Here, a new method of approach is derived for the proof of the existence of optimal control.

Theorem 3.1

Consider the system (1.1) given as :

$$\frac{d}{dt}[x(t) - g(t, x_t)] + A(t)x(t) = \int_0^t f(s, x_s)ds + \int_{-h}^0 (d_s C(s, l)u(s + l)) \dots \dots \dots (3.1)$$

with its standing hypothesis.

Suppose u^* is the optimal control of the system (3.1), then it is unique.

Proof:

Let u^* and v^* be optimal controls for the system (3.1), the u^* and v^* maximize

$$C^T \int_0^t \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right], \quad \text{for } t \in [0, a], \quad a > 0.$$

over all admissible controls $u \in U$, and so we have the inequality with u^* as the optimal control given below:

$$C^T \int_0^t \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] u(s) ds \leq C^T \int_0^{t^*} \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] u^*(s) ds \quad (3.2)$$

Also, using v^* as the optimal control, we have

$$\begin{aligned} C^T \int_0^t \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] u(s) ds \\ \leq C^T \int_0^{t^*} \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] u^*(s) ds \end{aligned} \quad (3.3)$$

Taking maximum of u over $[-1,1]$, the range of definition of u^* in (3.2) and (3.3), we have the equation

$$\begin{aligned} C^T \int_0^t \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] \max |u(s)| ds, \quad \text{for } -1 \leq s \leq 1. \\ = C^T \int_0^{t^*} \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] u^*(s) ds, \quad \text{for } u^* \in U \quad \dots \dots \dots (3.4) \end{aligned}$$

Also

$$C^T \int_0^t \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] \max |u(s)| ds, \quad \text{for } -1 \leq s \leq 1.$$

$$= C^T \int_0^{t^*} \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] v^*(s) ds, \text{ for } v^* \in U \quad \dots \dots \dots (3.5)$$

for $u, v^* \in U$, v^* being optimal and $-1 \leq s \leq 1$.

Subtracting equation (3.5) from (3.4), we have

$$0 = C^T \int_0^{t^*} \left[\int_{-h}^0 T(t-s) d_s \hat{C}(s-l, l) \right] \{ u^*(s) - v^*(s) \} ds$$

(since system (3.1) is controllable or proper).

$$\Rightarrow u^*(s) - v^*(s) = 0$$

$$\Rightarrow u^*(s) = v^*(s)$$

This establishes that optimal control is unique.

4. CONCLUSION

In this work, Neutral Functional Integro-differential systems in Banach spaces with Distributed Delays in the control were presented for optimal controllability analysis.

We established that an admissible control energy function of Neutral Functional Integro-differential systems in Banach spaces with Distributed Delays in the control is optimal control energy function of the system if and only if it is unique

The establishment of this uniqueness property of an optimal control energy function provides a new approach to proving the existence of an optimal control energy function of our system of interest..

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Author’s Brief Data



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Appraising Landscaping in Chukwuemeka Odumegwu Ojukwu University, Uli Campus, Anambra State, Nigeria

By

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ABSTRACT

Amid the growing benefits for proper landscaping design and planning, there is the need for man to be in a decent, well-organised and aesthetically pleasing environment. This could add value to concentration of staff and students in the campus as well as provide relaxation points within the campus. The landscaping quality of Uli campus of Chukwuemeka Odumegwu Ojukwu University deserves attention in view of its state. The objectives of this paper are to appraise the quality of the present status of landscaping in the campus and assess the perception of people on the quality of present landscape in the campus environment. This is with a view to providing a feedback for improved landscape management of the University campus environment. The methodology adopted for this research was survey design. The focus was on academic staff of the Faculty of Environmental Science of the university randomly selected from the research population. This selection was premised on their assumed knowledge of the subject matter. Data was collected from primary sources using questionnaires and observation schedules. Data analysis was done at the univariate level using Statistical Package for Social Sciences (SPSS). The outcomes show that the landscape environment within the campus is not in a good state. Some contributing factors to this were attributed to inadequate maintenance operations, inadequate provision of funds and inadequate equipment for maintenance operations, among others. The study recommends involving professionals in the built environment in the physical planning unit and works department of the institution to handle landscaping concerns within the campus, provision of enough funds for landscape improvement and maintenance operations, incorporating man-made features such as trash cans, street lights, sculpture, defined pedestrian walkways, paving and other road furnishings incorporated into the landscape. The university management may revive an existing landscape committee that would liaise with the horticulture unit of the faculty of Agriculture and have adequate as well as regular supply of new plants for possible replacement of dead plants and/or planting of new ones where they are desired. A redesign of the general landscape of the campus is desirable.

Keywords: assessment, campus, landscaping, maintenance, university

INTRODUCTION

Through designed landscapes, people can attain personal consciousness and responsibilities for the environment while letting go the pressures of everyday life. As such, landscaping plays a vital role in the quality of the environment as well as the physical and psychological wellbeing of the people. There have been tremendous changes in the building professions over time, as new advances brought new challenges that generate opportunities on the one hand, and present the probability of displacing those not prepared for it, on the other hand (Ogeye, Senibi & Akinboboye, 2019).

Landscaping refers to any activity that modifies the visible features of an area including the living elements, natural elements and man-made elements, while the landscape is everything one can see looking across an area of land. Landscape design can be seen as the art of designing and management of the components of landscape (i.e. Landforms, water bodies, vegetation and man-made features) to make good outdoor spaces for aesthetic purposes, useful, healthy and enjoyable purposes through application of cultural and scientific knowledge with concern for resources preservation (Adekunle & Basorun, 2016). Landscape practices comprise of the designing, installation and maintenance of the landscape design. Ayeni, Olotuah and Adedeji, (2013) noted that landscape design compliments architecture and provides the opportunity to contribute to the aesthetics of an area in order to improve the built environment. In addition, the principle of landscape design is to fuse the buildings with the environment, to achieve a well-planned environment.

Landscape design, as a separate discipline and business, is becoming conspicuous in the Architecture profession in Nigeria. Landscaping practices constitute a form of trade, which can be a veritable source of livelihood while serving the function of beautifying the physical environment. This prospect is yet to be fully realized in the country.

University campuses are expected to be distinguished in landscaping. A key way of achieving this is the use of well-defined landscapes, and these could be a means of attracting people to visit and to study. Good landscape design can, therefore, play a vital role in the enhancement of universities' environments and open spaces, by creating a nexus between aesthetics and open space management (Adekunle & Basorun, 2016). In pursuance of this, University campuses ought to denote landmarks as

spaces which indicate attractive spaces that represent campus identity, thus creating impressions of the campus environment as an exceptionally distinct institution. Unfortunately, poor attention has been given to the outdoor spaces around buildings in different university campuses in Nigeria. It can be shown that if considerable attention is given to the surroundings of the building structures, there will be an improvement in the environment.

Observations of the landscapes of university campus reveal such problems as the lack of outdoor landmark spaces, poor landscape design and poor landscape management. This situation naturally, negatively affects the associated academic and residential activities within the campus. For that reason, this study seeks to appraise the state of existing landscape in the campus, with a view to providing a framework/feedback for improving and sustaining the landscape management of the University campus environment. The objectives are to appraise the quality of the present landscaping in the campus and assess the perception of people on the quality of present landscape in the campus environment of Chukwuemeka Odumegwu Ojukwu University, Uli Campus Anambra State.

LITERATURE REVIEW

WiseGEEK (2012) as cited in Ayeni, Olotuah and Adedeji, (2013) stated that landscape architecture is a branch of architecture that deals with planning and design of land and its relation to the building around it. Wright, (2008) defined Landscape design as an art with the function of creating and preserving the beauty in the surroundings of human habitations as well as broader natural scenery of the country. Architecture ought to transcend the designing of buildings, and incorporate the transformation of the physical environment through proper design. This will improve the quality of the environment, as the combination of hard and soft landscape elements makes the environment ecofriendly.

The art of landscape practice pulls together elements to create an aesthetically pleasing extension of interior to outdoor living spaces (Asiedu, Buah, & Blankson, 2010). Hard landscape elements are non-living hard materials used by landscape designers to develop landscape designs. Examples of these are: rocks, stones, paving, gravel, steps, garden furniture and other man-made components of landscape. Soft landscape elements refer to living things brought into the landscape. Examples of these are plant materials such as: lawn, borders created with

trees, flowers and shrubs (Ogunsote, Adedeji, & Prucnal-Ogunsote, 2011).

Landscaping entails some of the following activities- growing/installation of plants, planning beautiful gardens, mow lawns, prune shrubs, erect fences (as enclosures), among others. Elf, (1996) as cited in Adekunle and Basorun, (2016) noted that a well-designed landscape helps to reduce erosion and global warming as well as prevent pollution of the environment. This is achieved since soft landscape elements used for landscape designs can improve air quality. Amongst several factors, landscaping, as an aspect of campus development and beautification needs to gradually gain acceptance and be transformed into a culture, which would gradually influence the university campus environment. Most of the plants that could be found on the University campus are native to the local environment, and could thus aid in the modification of the microclimate of the environment.

Good landscape management involves right plants selection, appropriate timing of plantings and plant maintenance techniques, maintenance of hardscapes when broken, among others. These are important towards realizing an attractive environment. Principally, the selections should be based on the functional roles the elements would play in the landscape (Ayeni & Adedeji, 2014). Maintenance involves the care and upkeep of the landscape after installation. Since landscapes change appearance and size over time, different types of maintenance works are required. These may include: weeding in lawns, replacement of dead plants, spraying of insecticides for insects and disease control, mowing of lawn, irrigation of lawn, repairing of paved surfaces, pruning of trees/shrubs, cleaning of fountains, repainting of outdoor furnishings and preventive maintenance on the equipment. Also of great importance is the quality of maintenance tools and equipment used in carrying out the exercise. Some of the tools/equipment used in the maintenance can be grouped into sophisticated and simple equipment. Examples include hand trowel, shears, shovel, crosscut saw, rake, wheel barrow, transplanting hoe, mower, sprinkler, hedge trimmer, shears, and cutlass.

STUDY AREA

Chukwuemeka Odumegwu Ojukwu University, Uli Campus, is situated in Uli, Ihiala Local Government Area of Anambra state. It is located on latitude 5°46'11"N and longitude 6°50'10"E. The University was established in year 2000 by the Anambra State Government with the name Anambra State University. The University was renamed to the

current name in the year 2014. Chukwuemeka Odumegwu Ojukwu University has three-campus arrangement – Igbariam (which is the seat of administration), Uli and Awka. There are six faculties in the Uli campus and they are: Engineering, Natural Sciences, Physical Sciences, Environmental Sciences, Basic Medical Sciences and Education. The Uli campus has lecture halls/classrooms, laboratories, library, offices, hostel, chaplaincy, banks and other businesses.

METHODOLOGY

The sources of data for this study were primary and secondary. The primary data were obtained through the administration of questionnaires and observation schedule. The secondary data were obtained from documents and research materials on staff strength and university campus master plan. The target population for this study are academic staff of the Faculty of Environmental Science of the university. This selection was premised on their assumed knowledge of the subject matter. Samples would be taken from each of the departments that make up the faculty. Owolabi, Ogunsajo, Bodunde and Olubode (2020) stated that landscaping is greatly valued by people with education of the environment based on their knowledge of elements used and the important roles they play in man’s environment.

Below is the number of academic staff of faculty of Environmental Science obtained from the university.

Staff Population in Sampled Unit

Target Population: Academic Staff of the Faculty of Environmental Science of Chukwuemeka Odumegwu Ojukwu University, Uli Campus

No. of Academic Staff: 41

Source: Authors field survey, 2023

30% of this research population was chosen as the sample size. In sampling ratio, St. Olaf College (2023) noted that for populations under 1,000, a minimum ratio of 30% is advisable to ensure representativeness of the sample. This gives a figure of 12, so 12 copies of questionnaire were randomly administered across the lecturers across the four (4) departments in the faculty.

FINDINGS AND DISCUSSION

Types of landscape elements dominant on campus

The results shown in Table 1 indicate that 41.7% of the respondents stated that softscape elements were dominant on campus, 25% stated that hardscape elements were dominant on campus while 33.3% stated that both hardscape and softscape elements are balanced on campus.

Table 1: Data on types of landscape elements dominant on campus

Value Label	Frequency	Valid Percent	Cumulative Percent
Softscape	5	41.7	41.7
Hardscape	3	25	66.7
Both hardscape and softscape	4	33.3	100.0
Total	12	100.0	

Source: Authors field survey, 2023

Quality of Landscaping Perception on Campus

The data obtained show that bulk of the respondents (58.3%) rated the quality of landscaping on campus as poor, 33.3% rated it as very poor. Also, a small percentage (8.3%) of the respondents rated it as good. These are illustrated in Table 2.

Table 2: Data on Quality of Landscaping Perception on Campus

Value Label	Frequency	Valid Percent	Cumulative Percent
Very poor	4	33.3	33.3
Poor	7	58.4	91.7
Neutral	-	0.0	0.0
Good	1	8.3	100.0
Very good	-	0.0	0.0
Total	12	100.0	

Source: Authors field survey, 2023

Factors Influencing the Quality of Landscaping on Campus

Data analysis on the factors influencing the quality of landscaping on campus and the perception of the respondents vary. Majority of them (58.3%) are of the opinion that inadequate provision of funds affects the quality, 25% attributed the quality to lack of capacity to carry out landscaping maintenance operations. 16.7% opined that the factor affecting the landscaping quality is poor maintenance culture as shown in figure 1. Akin to this, 75% of the respondents noted that there are no landscape maintenance operations done on campus while 25% stated that landscape maintenance operations done as need arises. This finding is

consistent with the opinions of Forbes and Kindle (2013) which stated that landscape should be properly maintained to sustain its quality.

Similarly, 83.3% suggested that both man-made elements and plant materials be incorporated into the landscaping to improve the beauty of the campus. 16.7% were of the view that only man-made elements are needed to improve the beauty of the campus.

The usage of softscape and hardscape elements can aid in regulating the microclimate around buildings and outdoor environment within the campus. The use of these softscape elements – trees and shrubs – is important in providing shades, wind breaking, improving air quality and adding to the beauty of the environment. The use of hardscape elements with less maintenance cost are important in order to prevent threats of floods and soil erosion as well as define car path within the campus.

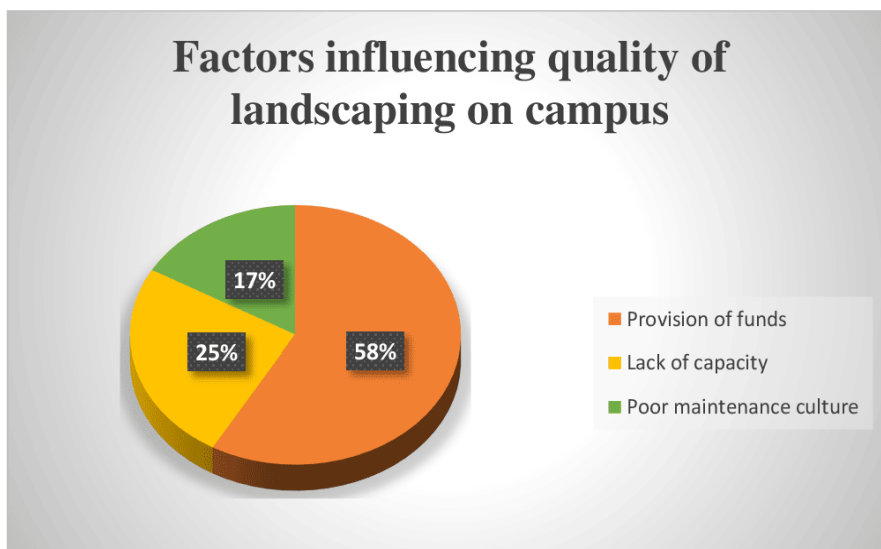


Figure1: Data on Factors Influencing the Quality of Landscaping on Campus

Source: Authors field survey, 2023

Type of equipment predominantly used in maintenance operations on Campus

The results from the analysis on type of equipment predominantly used in maintenance operations on campus show that majority (91.7%) of the respondents stated that simple equipment are used in the maintenance operations. 8.3% of the respondents stated that sophisticated equipment are used in the maintenance operations as shown in Figure 2. The simple equipment identified are machete/cutlass, hand shears and hoe are used in maintenance operations. The sophisticated equipment identified normally used is the riding mower.

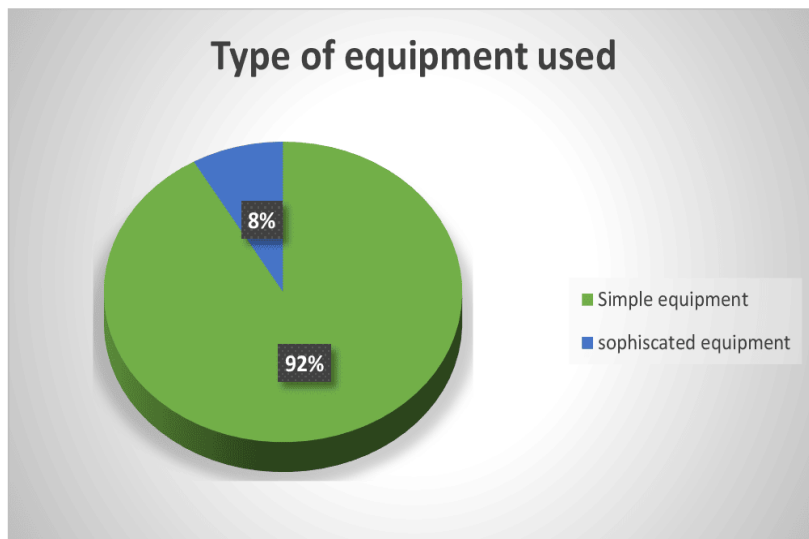


Figure 3: Data on type of equipment predominantly used in maintenance operations on campus
Source: (Authors' field survey, 2023)

CONCLUSION AND RECOMMENDATION

Proper landscaping practices have great potentials to uplift aesthetic status of campuses. There is the general acknowledgement of good landscaping as a suitable tool for improving environmental value of Uli campus, COOU. This can be achieved by devising a feasible idea to change the existing campus environment by the introduction of landscape features for good microclimate within the campus, neatness of the environment and for aesthetic purposes. Spaces that are not built up within the campus need to be designed and planned; structured management will entail proper maintenance practices.

The maintenance routine practices should be reviewed so there could be improvement in the state of the landscape within the campus. This can be achieved by involving professionals in the built environment in the physical planning unit and works department of the institution to handle landscaping concerns within the campus. The professionals should draft a programme chart of landscaping features for the improvement and sustenance of the beauty of the campus. The university administration may need to allocate more resources (human and funds) towards improvement of the campus. They can plan the release of funds in tranches based on the planned chart.

The equipment such as bush cutter, pruning shear, sprinkler, and hedge trimmer can be incorporated to the existing equipment in use for better output. Man-made features such as trash cans, street lights, road benches for sit-out, sculpture, defined pedestrian walkways, controls/ barriers

created to direct flow of movement, paving, road signs, etc can be incorporated into the landscape. Similarly, plant materials such as trees of diverse species, flowers of different colours, lawns should be improved upon to advance the aesthetic appeal of the campus. From the environmental point of view, these elements can serve as wind breakers; inhibit soil erosion and control ponding during the rainy season; as well as help to regulate the effect of global warming by maintaining in the atmosphere in the campus.

Since landscaping practices constitute a form of trade, which can be a source of income, the university management may consider opening horticulture unit where plants can be grown in the nursery and sold to members of the public.

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